

Integrability and limit cycles in polynomial systems of ODEs

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- Introduction to the center problem

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- Limit cycles: Cyclicity and 16th Hilbert problem

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- Algorithmic approach to the problems

A planar system with singular point at the origin:

$$\begin{aligned}\dot{x} &= ax + by + \sum_{p+q=2}^{\infty} \alpha_{pq} x^p y^q, \\ \dot{y} &= cx + dy + \sum_{p+q=2}^{\infty} \beta_{pq} x^p y^q.\end{aligned}\tag{1}$$

The linear approximation:

$$\begin{aligned}\dot{x} &= ax + by, \\ \dot{y} &= cx + dy\end{aligned}\tag{2}$$

$$A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}, \quad \tau = a + d, \quad \Delta = ad - bc$$

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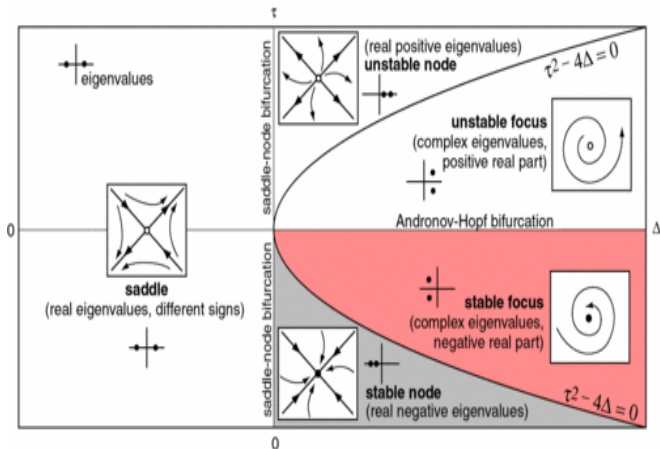
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- Topological picture of trajectories near the origin of (1) and (2) is equivalent,
- except of the case $\tau = 0, \Delta > 0$ (\Leftrightarrow the eigenvalues of A are $\pm i\omega$).



$\tau = 0, \Delta > 0$ (\Leftrightarrow the eigenvalues of A are $\pm i\omega$) - a center for linear system;
 in the case of nonlinear system: **either a center or a focus.**

- A center \iff all solutions near the origin are periodic.
- A focus \iff all solutions near the origin are spirals.

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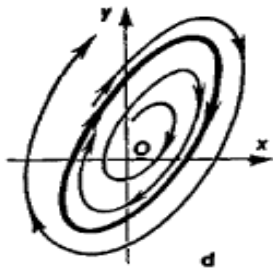
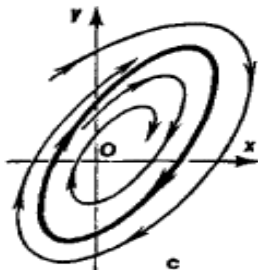
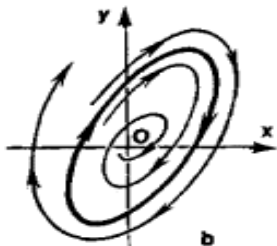
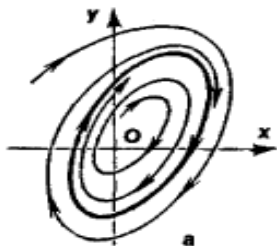
Poincaré center problem

How to distinguish if the system

$$\begin{aligned}\dot{x} &= \omega y + \sum_{p+q=2}^{\infty} \alpha_{pq} x^p y^q, \\ \dot{y} &= -\omega x + \sum_{p+q=2}^{\infty} \beta_{pq} x^p y^q\end{aligned}$$

has a center or a focus at the origin?

Limit cycles



$$\dot{x} = P_n(x, y), \quad \dot{y} = Q_n(x, y), \quad (A)$$

$P_n(x, y)$, $Q_n(x, y)$, are polynomials of degree n .

Let $h(P_n, Q_n)$ be the number of limit cycles of system (A) and let $H(n) = \sup h(P_n, Q_n)$.

The question of the second part of the 16th Hilbert's problem:

- find a bound for $H(n)$ as a function of n .

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The problem is still unresolved even for $n = 2$.

$n = 2$

- I. Petrovskii, E. Landis, On the number of limit cycles of the equation $dy/dx = P(x,y)/Q(x,y)$, where P and Q are polynomials of 2nd degree (Russian), Mat. Sb. N.S. 37(79) (1955), 209-250
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Song Ling Shi, A concrete example of the existence of four limit cycles for plane quadratic systems, Sci. Sinica 23 (1980), 153-158

- A simpler problem: is $H(n)$ finite? Unresolved.

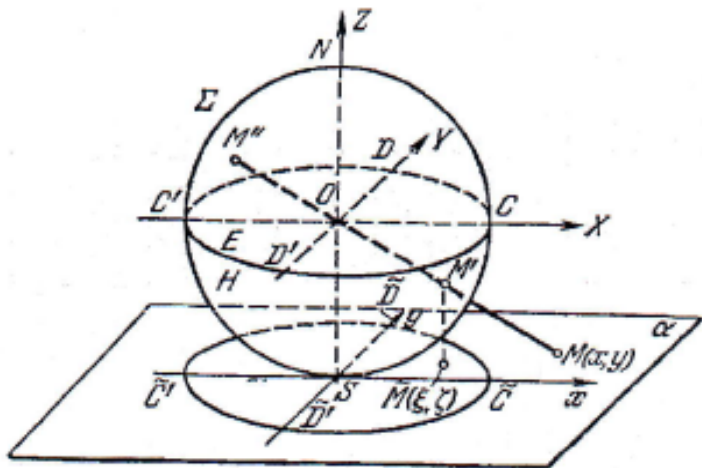
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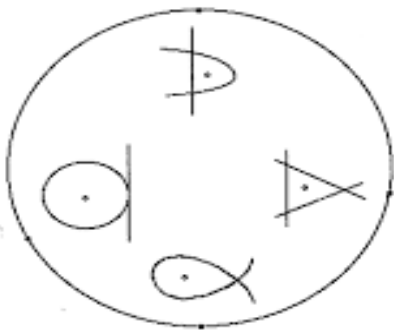
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Around 1980 Yu. Ilyashenko found a mistake in Dulac's proof.

Poincaré compactification



Separatrix cycles:



Dulac's mistake

A germ of a map $f : (R^+, 0) \rightarrow (R^+, 0)$ is a semi-regular, if it is smooth in a neighborhood of 0 and admits an asymptotic expansion of the form

$$\hat{f}(x) = cx^{\nu_0} + \sum_j P_j(\ln x)x^{\nu_j},$$

where $c > 0$, $0 < \nu_j \rightarrow \infty$, $j > 0$, and P_j are real polynomials.

\hat{f} is an asymptotic expansion of f , if $\forall \nu > 0 \exists$ a partial sum of \hat{f} , which approximates f with accuracy better than x^ν , when $x \rightarrow 0$.

Dulac's theorem

For any polycycle of an analytic vector field, a cross-section with the vertex zero on the polycycle may be so chosen that the corresponding Poincaré map will be flat, inverse to flat, or semiregular.

Dulac's lemma

Let a semiregular map have an infinite number of fixed points.
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Counterexample

$$f(x) = x + \left(\sin \frac{1}{x}\right) e^{-\frac{1}{x}}$$

- Chicone and Shafer (1983) proved that for $n = 2$ a fixed system (A) has only finite number of limit cycles in any bounded region of the phase plane.

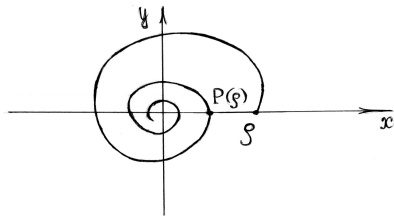
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- Bamòn (1986) and V. R (1986) proved that $h(P_2, Q_2, a^*, b^*)$ is finite.
- Il'yashenko (1991) and Ecalle (1992): $h(P_n, Q_n, a^*, b^*)$ is finite for any n .

The center problem and the local 16th Hilbert problem

Poincaré return map:

$$\dot{u} = -v + \sum_{i+j=2}^n \alpha_{ij} u^i v^j, \quad \dot{v} = u + \sum_{i+j=2}^n \beta_{ij} u^i v^j. \quad (3)$$



$$\mathcal{P}(\rho) = \rho + \eta_3(\alpha_{ij}, \beta_{ij})\rho^3 + \eta_4(\alpha_{ij}, \beta_{ij})\rho^4 + \dots$$

Center: $\eta_3 = \eta_4 = \eta_5 = \dots = 0$.

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Poincaré center problem

Find all systems in the family

$$\dot{u} = -v + \sum_{i+j=2}^n \alpha_{ij} u^i v^j, \quad \dot{v} = u + \sum_{i+j=2}^n \beta_{ij} u^i v^j,$$

which have a center at the origin.

Bautin ideal: $\mathcal{B} = \langle \eta_3, \eta_4, \dots \rangle \subset \mathbb{R}[\alpha_{ij}, \beta_{ij}]$.

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Bautin ideal: $\mathcal{B} = \langle \eta_3, \eta_4, \dots \rangle \subset \mathbb{R}[\alpha_{ij}, \beta_{ij}]$.

Algebraic counterpart

Find the variety $\mathbf{V}(\mathcal{B})$ of the Bautin ideal \mathcal{B} $\mathcal{B} = \langle \eta_3, \eta_4, \eta_5 \dots \rangle$.

$$\mathbf{V}(\mathcal{B}) = \{(\alpha_{ij}, \beta_{ij}) \in \mathcal{E} \mid \eta_3(\alpha_{ij}, \beta_{ij}) = \eta_4(\alpha_{ij}, \beta_{ij}) = \dots = 0\}$$

• $\mathbf{V}(\mathcal{B})$ is called the center variety.

$$\dot{u} = -v + \sum_{j+l=2}^n \alpha_{jl} u^j v^l, \quad \dot{v} = u + \sum_{j+l=2}^n \beta_{jl} u^j v^l \quad (4)$$

Poincare map:

$$\mathcal{P}(\rho) = \rho + \eta_2(\alpha_{ij}, \beta_{ij})\rho^2 + \eta_3(\alpha_{ij}, \beta_{ij})\rho^3 + \dots + \eta_k(\alpha_{ij}, \beta_{ij})\rho^k + \dots$$

Let $\mathcal{B} = \langle \eta_3, \eta_4, \dots \rangle \subset \mathbb{R}[\alpha_{ij}, \beta_{ij}]$ be the ideal generated by all focus quantities η_i . There is k such that

$$\mathcal{B} = \langle \eta_{u_1}, \eta_{u_2}, \dots, \eta_{u_k} \rangle.$$

The Bautin ideal and Bautin's theorem

Then for any s

$$\eta_s = \eta_{u_1} \theta_1^{(s)} + \eta_{u_2} \theta_2^{(s)} + \cdots + \eta_{u_k} \theta_k^{(k)},$$

$$\mathcal{P}(\rho) - \rho = \eta_{u_1} (1 + \mu_1 \rho + \dots) \rho^{u_1} + \cdots + \eta_{u_k} (1 + \mu_k \rho + \dots) \rho^{u_k}.$$

Bautin's Theorem

If $\mathcal{B} = \langle \eta_{u_1}, \eta_{u_2}, \dots, \eta_{u_k} \rangle$ then the cyclicity of system (4) (i.e. the maximal number of limit cycles which appear from the origin after small perturbations) is less or equal to k .

Proof. Bautin N.N. Mat. Sb. (1952) v.30, 181-196 (Russian);

Trans. Amer. Math. Soc. (1954) v.100

Roussarie R. Bifurcations of planar vector fields and Hilbert's 16th problem (1998), Birkhauser.

The cyclicity problem

Find an upper bound for the maximal number of limit cycles in a neighborhood of a center or a focus

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Find an upper bound for the maximal number of limit cycles in a neighborhood of a center or a focus

By Bautin's theorem:

Algebraic counterpart

Find a basis for the Bautin ideal $\langle \eta_3, \eta_4, \eta_5, \dots \rangle$ generated by all coefficients of the Poincaré map

A basis of an ideal and its zero set

Radical of an ideal I is the set of all polynomials f such that some positive integer ℓ $f^\ell \in I$.

Strong Hilbert Nullstellensatz

Let $f \in \mathbb{C}[x_1, \dots, x_m]$ and let I be an ideal of $\mathbb{C}[x_1, \dots, x_m]$. Then f vanishes on the variety of I if and only if f belongs to the radical of I .

Corollary

If polynomials f_1, \dots, f_s from an ideal I define the variety of I , $\mathbf{V}(I) = \mathbf{V}(f_1, \dots, f_s)$, and the ideal I is a radical ideal (that is, $I = \sqrt{I}$), then $I = \langle f_1, \dots, f_s \rangle$.

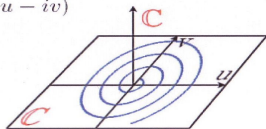
Holds only over \mathbb{C} !

Complexification

Complexification: $x = u + iv$ ($\bar{x} = u - iv$)

$$\dot{x} = i\left(x - \sum_{p+q=1}^{n-1} a_{pq}x^{p+1}\bar{x}^q\right)$$

$$\dot{\bar{x}} = -i\left(\bar{x} - \sum_{p+q=1}^{n-1} \bar{a}_{pq}\bar{x}^{p+1}x^q\right)$$



$$\dot{x} = i\left(x - \sum_{p+q=1}^{n-1} a_{pq}x^{p+1}y^q\right), \quad \dot{y} = -i\left(y - \sum_{p+q=1}^{n-1} b_{qp}x^qy^{p+1}\right) \quad (5)$$

The change of time $d\tau = idt$ transforms (5) to the system

$$\dot{x} = \left(x - \sum_{p+q=1}^{n-1} a_{pq}x^{p+1}y^q\right), \quad \dot{y} = -\left(y - \sum_{p+q=1}^{n-1} b_{qp}x^qy^{p+1}\right). \quad (6)$$

Poincaré-Lyapunov Theorem

The system

$$\frac{du}{dt} = -v + \sum_{i+j=2}^n \alpha_{ij} u^i v^j, \quad \frac{dv}{dt} = u + \sum_{i+j=2}^n \beta_{ij} u^i v^j \quad (7)$$

has a center at the origin if and only if it admits a first integral of the form

$$\Phi = u^2 + v^2 + \sum_{k+l \geq 2} \phi_{kl} u^k v^l.$$

Definition of a center for complex systems

System

$$\dot{x} = \left(x - \sum_{p+q=1}^{n-1} a_{pq} x^{p+1} y^q\right) = P, \quad \dot{y} = -\left(y - \sum_{p+q=1}^{n-1} b_{qp} x^q y^{p+1}\right) = Q, \quad (8)$$

has a center at the origin if it admits a first integral of the form

$$\Phi(x, y; a_{10}, b_{10}, \dots) = xy + \sum_{s=3}^{\infty} \sum_{j=0}^s v_{j,s-j} x^j y^{s-j}$$

For the complex system

$$\dot{x} = \left(x - \sum_{p+q=1}^{n-1} a_{pq} x^{p+1} y^q\right) = P, \quad \dot{y} = -\left(y - \sum_{p+q=1}^{n-1} b_{qp} x^q y^{p+1}\right) = Q,$$

one looks for a function

$$\Phi(x, y; a_{10}, b_{10}, \dots) = xy + \sum_{s=3}^{\infty} \sum_{j=0}^s v_{j,s-j} x^j y^{s-j}$$

such that

$$\frac{\partial \Phi}{\partial x} P + \frac{\partial \Phi}{\partial y} Q = g_{11}(xy)^2 + g_{22}(xy)^3 + \dots, \quad (9)$$

and g_{11}, g_{22}, \dots are polynomials in a_{pq}, b_{qp} . These polynomials are called *focus quantities*.

The Bautin ideal

The ideal $\mathcal{B} = \langle g_{11}, g_{22}, \dots \rangle$ generated by the focus quantities is called the *Bautin ideal*.

Center Problem

Find the variety $\mathbf{V}(\mathcal{B})$ of the Bautin ideal $\mathcal{B} = \langle g_{11}, g_{22}, g_{33} \dots \rangle$.

Definition

The variety of the Bautin ideal $\mathbf{V}(\mathcal{B})$ is called the center variety of the system.

By the Hilbert Basis Theorem there is an integer m that $\mathcal{B} = \langle g_{11}, \dots, g_{mm} \rangle$, however it is a difficult problem to find such m . A practical approach is as follows.

- Compute polynomials g_{ss} until the chain of varieties (considering as complex varieties) $V(\mathcal{B}_1) \supseteq V(\mathcal{B}_2) \supseteq V(\mathcal{B}_3) \supseteq \dots$ stabilizes (here $\mathcal{B}_k = \langle g_{11}, \dots, g_{kk} \rangle$), that is, until we find k_0 such that $V(\mathcal{B}_{k_0}) = V(\mathcal{B}_{k_0+1})$.

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To check that two varieties are equal we use

Radical Membership Test

$I = \langle f_1, \dots, f_s \rangle \in k[x_1, \dots, x_n]$, $f \in k[x_1, \dots, x_n]$.

$f \equiv 0$ on $V(I) \iff$ Groebner basis of the ideal $I = \langle f_1, \dots, f_s, 1 - f \rangle$ is $\{1\}$.

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- **Show that $V(\mathcal{B}_{k_0}) = V(\mathcal{B})$, that is, that each systems from $V(\mathcal{B}_{k_0})$ admits a first integral of the form (9).**

The center problem is solved for:

- quadratic system: $\dot{x} = x + P_2(x, y)$, $\dot{y} = -y + Q_2(x, y)$
by Dulac (1908) (by Kapteyn (1912) for real systems)

- the linear center perturbed by 3rd degree homogeneous polynomials:

$$\dot{x} = x + P_3(x, y), \quad \dot{y} = -y + Q_3(x, y)$$

by Sadovskii (1974) (by Malkin (1964) for real systems)

- for some particular subfamilies of the cubic system

$$\dot{x} = x + P_2(x, y) + P_3(x, y), \quad \dot{y} = -y + Q_2(x, y) + Q_3(x, y)$$

- for Lotka-Volterra quartic systems with homogeneous nonlinearities

$$\dot{x} = x + xP_3(x, y), \quad \dot{y} = -y + yQ_3(x, y)$$

by B. Ferčec, J. Giné, Y. Liu and V. R. (2013)

- for Lotka-Volterra quintic systems with homogeneous nonlinearities

$$\dot{x} = x + xP_4(x, y), \quad \dot{y} = -y + yQ_4(x, y)$$

by J. Giné and V. R. (2010)

The center variety of the quadratic system

$$\dot{x} = x - a_{10}x^2 - a_{01}xy - a_{-12}y^2, \quad \dot{y} = -(y - b_{10}xy - b_{01}y^2 - b_{2,-1}x^2). \quad (10)$$

Theorem (H. Dulac 1908, C. Christopher & C. Rousseau, 2001)

The variety of the Bautin ideal of system (10) coincides with the variety of the ideal $\mathcal{B}_3 = \langle g_{11}, g_{22}, g_{33} \rangle$ and consists of four irreducible components:

- 1) $\mathbf{V}(J_1)$, where $J_1 = \langle 2a_{10} - b_{10}, 2b_{01} - a_{01} \rangle$,
- 2) $\mathbf{V}(J_2)$, where $J_2 = \langle a_{01}, b_{10} \rangle$,
- 3) $\mathbf{V}(J_3)$, where $J_3 = \langle 2a_{01} + b_{01}, a_{10} + 2b_{10}, a_{01}b_{10} - a_{-12}b_{2,-1} \rangle$,
- 4) $\mathbf{V}(J_4) = \langle f_1, f_2, f_3, f_4, f_5 \rangle$, where

$$f_1 = a_{01}^3 b_{2,-1} - a_{-12} b_{10}^3, \quad f_2 = a_{10} a_{01} - b_{01} b_{10},$$

$$f_3 = a_{10}^3 a_{-12} - b_{2,-1} b_{01}^3,$$

$$f_4 = a_{10} a_{-12} b_{10}^2 - a_{01}^2 b_{2,-1} b_{01}, \quad f_5 = a_{10}^2 a_{-12} b_{10} - a_{01} b_{2,-1} b_{01}^2.$$

Proof. Computing the first three focus quantities we have

$$g_{11} = a_{10}a_{01} - b_{10}b_{01},$$

$$g_{22} = a_{10}a_{-12}b_{10}^2 - a_{01}^2b_{01}b_{2,-1} - \frac{2}{3}(a_{-12}b_{10}^3 - a_{01}^3b_{2,-1}) -$$

$$\frac{2}{3}(a_{01}b_{01}^2b_{2,-1} - a_{10}^2a_{-12}b_{10}),$$

$$g_{33} = -\frac{5}{8}(-a_{01}a_{-12}b_{10}^4 + 2a_{-12}b_{01}b_{10}^4 + a_{01}^4b_{10}b_{2,-1} - 2a_{01}^3b_{01}b_{10}b_{2,-1} - 2a_{10}a_{-12}^2b_{10}^2b_{2,-1} + a_{-12}^2b_{10}^3b_{2,-1} - a_{01}^3a_{-12}b_{2,-1}^2 + 2a_{01}^2a_{-12}b_{01}b_{2,-1}^2).$$

Using the radical membership test we see that

$$g_{22} \notin \sqrt{\langle g_{11} \rangle}, \quad g_{33} \notin \sqrt{\langle g_{11}, g_{22} \rangle}, \quad g_{44}, g_{55}, g_{66} \in \sqrt{\langle g_{11}, g_{22}, g_{33} \rangle},$$

i.e., $\mathbf{V}(\mathcal{B}_1) \supset \mathbf{V}(\mathcal{B}_3) \supset \mathbf{V}(\mathcal{B}_3) = \mathbf{V}(\mathcal{B}_4) = \mathbf{V}(\mathcal{B}_5)$. We expect that

$$\mathbf{V}(\mathcal{B}_3) = \mathbf{V}(\mathcal{B}). \quad (11)$$

The inclusion $\mathbf{V}(\mathcal{B}) \subseteq \mathbf{V}(\mathcal{B}_3)$ is obvious, therefore in order to check that (11) indeed holds we only have to prove that

$$\mathbf{V}(\mathcal{B}_3) \subseteq \mathbf{V}(\mathcal{B}). \quad (12)$$

To do so, we first look for a decomposition of the variety $\mathbf{V}(\mathcal{B}_3)$.

SINGULAR /

A Computer Algebra System for Polynomial Computations / ver

0<

by: G.-M. Greuel, G. Pfister, H. Schoenemann \ Aug

FB Mathematik der Universitaet, D-67653 Kaiserslautern \

```
LIB "primdec.lib";
```

```
ring r= 0, (a10,a01,a12,b21,b10,b01),lp;
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```
poly g11=a01*a10 - b01*b10;
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```
poly g22=...
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```
poly g33=...
```

```
ideal i=g11,g22,g33;
```

```
minAssGTZ(i);
```


[1]:

```
_ [1]=a01^3*b21-a12*b10^3  
_ [2]=a10*a12*b10^2-a01^2*b21*b01  
_ [3]=a10*a01-b10*b01  
_ [4]=a10^2*a12*b10-a01*b21*b01^2  
_ [5]=a10^3*a12-b21*b01^3
```

[2]:

```
_ [1]=b10  
_ [2]=a01
```

[3]:

```
_ [1]=a01-2*b01  
_ [2]=2*a10-b10
```

[4]:

```
_ [1]=2*a12*b21+b10*b01  
_ [2]=2*a01+b01  
_ [3]=a10+2*b10
```

To verify that (12) holds there remains to show that every system (10) with coefficients from one of the sets $\mathbf{V}(J_1), \mathbf{V}(J_2), \mathbf{V}(J_3), \mathbf{V}(J_4)$ has a center at the origin, that is, there is a first integral $\Psi(x, y) = xy + h.o.t.$

Systems corresponding to the points of $\mathbf{V}(J_1)$ are Hamiltonian with the Hamiltonian

$$H = -\left(xy - \frac{a_{-12}}{3}y^3 - \frac{b_{2,-1}}{3}x^3 - a_{10}x^2y - b_{01}xy^2\right)$$

and, therefore, have centers at the origin (since $D(H) \equiv 0$).

To show that for the systems corresponding to the components $\mathbf{V}(J_2)$ and $\mathbf{V}(J_3)$ the origin is a center we use the Darboux method.

$$\dot{x} = P(x, y), \quad \dot{y} = Q(x, y), \quad x, y \in \mathbb{C} \quad P, Q \text{ are polynomials.} \quad (13)$$

The polynomial $f(x, y) \in \mathbb{C}[x, y]$ defines an *algebraic invariant curve* $f(x, y) = 0$ of system (13) if there exists a polynomial $k(x, y) \in \mathbb{C}[x, y]$ such that

$$D(f) := \frac{\partial f}{\partial x} P + \frac{\partial f}{\partial y} Q = kf. \quad (14)$$

The polynomial $k(x, y)$ is called a *cofactor* of f .

Suppose that the curves defined by

$$f_1 = 0, \dots, f_s = 0$$

are invariant algebraic curves of system (13) with the cofactors k_1, \dots, k_s . If

$$\sum_{j=1}^s \alpha_j k_j = 0, \quad (15)$$

then $H = f_1^{\alpha_1} \dots f_s^{\alpha_s}$ is a (Darboux) first integral of the system (13).

Systems from $\mathbf{V}(J_2)$ and $\mathbf{V}(J_3)$ admit Darboux integrals.

Consider the variety $\mathbf{V}(J_3)$. In this case the system is

$$\begin{aligned} \dot{x} &= x - a_{10}x^2 + \frac{b_{01}}{2}xy - \frac{a_{10}b_{01}}{4b_{2,-1}}y^2, \\ -\dot{y} &= (y - b_{01}y^2 + \frac{a_{10}}{2}xy - b_{2,-1}x^2). \end{aligned} \quad (16)$$

- $f = \sum_{i+j=0}^n c_{ij} x^i y^j$, $k = \sum_{i+j=0}^{m-1} d_{ij} x^i y^j$. (m is the degree of the system; in our case $m = 1$). To find a bound for n is the Poincaré problem (unresolved).
- Equal the coefficients of the same terms in $D(f) = kf$.
- Solve the obtained system of polynomial equations for unknown variables c_{ij}, d_{ij} .

$$\ell_1 = 1 + 2 b_{10} x - a_{01} b_{2,-1} x^2 + 2 a_{01} y + 2 a_{01} b_{10} x y - \frac{a_{01} b_{10}^2}{b_{2,-1}} y^2,$$

$$\begin{aligned} \ell_2 = & (2 b_{10} b_{2,-1}^2 + 6 b_{10}^2 b_{2,-1}^2 x + 3 b_{10}^3 b_{2,-1}^2 x^2 - 3 a_{01} b_{10} b_{2,-1}^3 x^2 - a_{01} b_{10}^2 b_{2,-1}^3 \\ & 6 a_{01} b_{10} b_{2,-1}^2 y - 3 b_{10}^4 b_{2,-1} x y + 6 a_{01} b_{10}^2 b_{2,-1}^2 x y - 3 a_{01}^2 b_{2,-1}^3 x y + 3 a_{01} b_{10}^3 b_{2,-1}^2 \\ & 3 a_{01}^2 b_{10} b_{2,-1}^3 x^2 y - 3 a_{01} b_{10}^3 b_{2,-1} y^2 + 3 a_{01}^2 b_{10} b_{2,-1}^2 y^2 - 3 a_{01} b_{10}^4 b_{2,-1} x y^2 + 3 a_{01}^2 \\ & a_{01} b_{10}^5 y^3 - a_{01}^2 b_{10}^3 b_{2,-1} y^3) / (2 b_{10} b_{2,-1}^2) \end{aligned}$$

with the cofactors $k_1 = 2(b_{10}x - a_{01}y)$ and $k_2 = 3(b_{10}x - a_{01}y)$.
The equation

$$\alpha_1 k_1 + \alpha_2 k_2 = 0$$

has a solution $\alpha_1 = -3, \alpha_2 = 2, \implies$

$$\Psi = \ell_1^{-3} \ell_2^2 \equiv c.$$

Thus, every system from $\mathbf{V}(J_3)$ has a center at the origin.

Systems from $\mathbf{V}(J_4)$ are time-reversible

$$\frac{dz}{dt} = F(z) \quad (z \in \Omega), \quad (17)$$

Ω is a manifold.

Definition

A (time-)reversible symmetry of (17) is an involution $R : \Omega \mapsto \Omega$, such that

$$R_* \mathcal{X}_F = -\mathcal{X}_F \circ R. \quad (18)$$

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$$\dot{u} = v + vf(u, v^2), \quad \dot{v} = -u + g(u, v^2), \quad (19)$$

$$u \rightarrow u, \quad v \rightarrow -v, \quad t \rightarrow -t$$

leaves the system unchanged \Rightarrow the u -axis is a line of symmetry for the orbits \Rightarrow no trajectory in a neighbourhood of $(0, 0)$ can be a spiral \Rightarrow the origin is a center.

Here $R : u \mapsto u, v \mapsto -v$.

$$\begin{aligned}\dot{x} &= x - \sum a_{pq} x^{p+1} y^q = P(x, y), \\ \dot{y} &= -y + \sum b_{qp} x^q y^{p+1} = Q(x, y),\end{aligned}\tag{20}$$

The condition of time-reversibility

$$\gamma Q(\gamma y, x/\gamma) = -P(x, y), \quad \gamma Q(x, y) = -P(\gamma y, x/\gamma).$$

\implies (20) is time-reversible if and only if

$$b_{qp} = \gamma^{p-q} a_{pq}, \quad a_{pq} = b_{qp} \gamma^{q-p}.\tag{21}$$



$$a_{p_k q_k} = t_k, \quad b_{q_k p_k} = \gamma^{p_k - q_k} t_k\tag{22}$$

for $k = 1, \dots, \ell$. (22) define a surface in the affine space

$$\mathbb{C}^{3\ell+1} = (a_{p_1 q_1}, \dots, a_{p_\ell q_\ell}, b_{q_\ell p_\ell}, \dots, b_{q_1 p_1}, t_1, \dots, t_\ell, \gamma).$$

- The set of all time-reversible systems is the projection of this surface onto $\mathbb{C}^{2\ell}$.
- To find this set we have to eliminate t_k and γ from (22).

For an ideal $I \subset k[x_1, \dots, x_n]$ the ℓ -elimination ideal of I is the ideal $I_\ell = I \cap k[x_{\ell+1}, \dots, x_n]$.

Elimination Theorem

Fix the lexicographic term order on the ring $k[x_1, \dots, x_n]$ with $x_1 > x_2 > \dots > x_n$ and let G be a Gröbner basis for an ideal I of $k[x_1, \dots, x_n]$ with respect to this order. Then for every ℓ , $0 \leq \ell \leq n - 1$, the set $G_\ell := G \cap k[x_{\ell+1}, \dots, x_n]$ is a Gröbner basis for the ℓ -th elimination ideal I_ℓ .

$\mathbf{V}(I_\ell)$ is the smallest affine variety containing $\pi_\ell(V) \subset \mathbb{C}^{n-\ell}$
($\mathbf{V}(I_\ell)$ is the Zariski closure of $\pi_\ell(V)$).

$$H = \langle a_{p_k q_k} - t_k, b_{q_k p_k} - \gamma^{p_k - q_k} t_k \mid k = 1, \dots, \ell \rangle, \quad (23)$$

Let \mathcal{R} be the set of all time-reversible systems in the family (20).

Theorem

(V. R., Open Syst. Inf. Dyn., 2008) 1)

$\overline{\mathcal{R}} = \mathbf{V}(\mathcal{I}_R)$ where $\mathcal{I}_R = \mathbb{C}[a, b] \cap H$, that is, the Zariski closure of the set \mathcal{R} of all time-reversible systems is the variety of the ideal \mathcal{I}_R .

2) Every system (20) from $\overline{\mathcal{R}}$ admits an analytic first integral of the form $\Psi = xy + \dots$

For the quadratic system the elimination gives exactly the ideal J_4

\implies

each system from $\mathbf{V}(J_4)$ also has a center at the origin.

Mechanisms for integrability

- Darboux integrability
- Hamiltonian systems
- Time-reversibility

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- Open problem:
What is the complete list of mechanisms for integrability?

The cyclicity of the quadratic system

Generalized Bautin's theorem (V. R. & D. Shafer, 2009)

If the ideal \mathcal{B} of all focus quantities of system

$$\dot{x} = \left(x - \sum_{p+q=1}^{n-1} a_{pq}x^{p+1}y^q\right), \quad \dot{y} = -\left(y - \sum_{p+q=1}^{n-1} b_{qp}x^qy^{p+1}\right)$$

is generated by the m first focus quantities,

$\mathcal{B} = \langle g_{11}, g_{22}, \dots, g_{mm} \rangle$, then at most m limit cycles bifurcate from the origin of the corresponding real system

$$\dot{u} = \lambda u - v + \sum_{j+l=2}^n \alpha_{jl}u^jv^l, \quad \dot{v} = u + \lambda v + \sum_{j+l=2}^n \beta_{jl}u^jv^l,$$

that is the cyclicity of the system is less or equal to m .

The problem has been solved for:

- The quadratic system ($\dot{x} = P_n, \dot{y} = Q_n, n = 2$) - Bautin (1952) (Żołądek (1994), Yakovenko (1995), Françoise and Yomdin (1997), Han, Zhang & Zhang (2007)).
- The system with homogeneous cubic nonlinearities - Sibirsky (1965) (Żołądek (1994))

In both cases the analysis is relatively simple because the Bautin ideal is a radical ideal.

Bautin's theorem for the quadratic system

The cyclicity of the origin of system

$$\dot{u} = \lambda u - v + \alpha_{20}u^2 + \alpha_{11}uv + \alpha_{02}v^2, \quad \dot{v} = u + \lambda v + \beta_{20}u^2 + \beta_{11}uv + \beta_{02}v^2$$

equals three.

Proof. (V. R., 2007) We have for all k

$$g_{kk} |_{\mathbf{v}(\mathcal{B}_3)} \equiv 0 \quad (24)$$

where $\mathcal{B}_3 = \langle g_{11}, g_{22}, g_{33} \rangle$.

Hence, if \mathcal{B}_3 is a radical ideal then (24) and Hilbert Nullstellensatz yield that $g_{kk} \in \mathcal{B}_3$. Thus, to prove that an upper bound for the cyclicity is equal to three it is sufficient to show that \mathcal{B}_3 is a radical ideal.

With help of SINGULAR we check that

$$\text{std}(\text{radical}(\mathcal{B}_3)) = \text{std}(\mathcal{B}_3). \quad (25)$$

Hence, $\mathcal{B}_3 = \mathcal{B}$. This completes the proof.

The cyclicity problem can be "easily" solved if the Bautin ideal is radical.

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An approach which works for some systems with non-radical Bautin ideal:

- - V. Levandovskyy, V. R. , D. S. Shafer, The cyclicity of a cubic system with non-radical Bautin ideal, J. Differential Equations, 246 (2009) 1274-1287.
- V. Levandovskyy, G. Pfister and V. R. Evaluating cyclicity of cubic systems with algorithms of computational algebra, Communications in Pure and Applied Analysis, **11** (2012) 2023 - 2035.

Another point of view at the center problem

$$\dot{x} = (x - \sum_{i+j=1}^{n-1} a_{ij}x^{i+1}y^j) = P, \quad \dot{y} = -(y - \sum_{i+j=1}^{n-1} b_{ji}x^jy^{i+1}) = Q, \quad (26)$$

$$\Phi(x, y; a_{10}, b_{10}, \dots) = xy + \sum_{s=3}^{\infty} \sum_{k=0}^s v_{k, s-k} x^k y^{s-k}$$

$$W = \sum W_{(\nu_1, \nu_2, \dots, \nu_{2l})} a_{10}^{\nu_1} a_{01}^{\nu_2} \dots a_{p_\ell, q_\ell}^{\nu_\ell} b_{q_\ell, p_\ell}^{\nu_{\ell+1}} \dots b_{10}^{\nu_{2\ell-1}} b_{01}^{\nu_{2\ell}} \quad (27)$$

be a formal series with $W(\bar{0}) = 1$. Denote $|a| = \sum a_{ij}$, $|b| = \sum b_{ij}$,

$$\mathcal{A}(W) = \sum \frac{\partial W}{\partial a_{ij}} a_{ij} (i-j-i|a|+j|b|) + \sum \frac{\partial W}{\partial b_{ij}} b_{ij} (i-j-i|a|+j|b|). \quad (28)$$

Theorem

System (26) has a center at the origin for all values of the parameters a_{kn}, b_{nk} if and only if there is a formal series (27) satisfying the equation

$$\mathcal{A}(W) = W(|a| - |b|). \quad (29)$$

There is a ring \mathcal{P} of some functions of a, b such that the following diagram is commutative

$$\begin{array}{ccc}
 \mathcal{P}[[x, y]] & \xrightarrow{\pi} & \mathcal{P} \\
 D \downarrow & & \downarrow \mathcal{A} \\
 \mathcal{P}[[x, y]] & \xrightarrow{\pi} & \mathcal{P},
 \end{array} \tag{30}$$

where π is an isomorphism defined by

$$\pi : \sum c_{\alpha, \beta}(a, b)x^{\alpha}y^{\beta} \longrightarrow \sum c_{\alpha, \beta}(a, b), \tag{31}$$

and $D(\Phi)$ is the operator

$$D(\Phi) := \frac{\partial \Phi}{\partial x} P + \frac{\partial \Phi}{\partial y} Q.$$

If we consider a system which has a Darboux integral

$$f_1^{\alpha_1} f_2^{\alpha_2} \dots f_s^{\alpha_s}$$

then the exponents α_i are, generally speaking, functions of the coefficients a_{ij} , b_{ji} of our system. Therefore, noting that for w_i of the form $w_i = 1 + h.o.t$ the property $\mathcal{A}(w_i) = k_i w_i$ yields

$$\mathcal{A}(\log w_i) = k_i,$$

we see that an analog of the equations for the cofactors in the Darboux method is the equation

$$\sum_{i=1}^s \alpha_i k_i + \sum_{i=1}^s \mathcal{A}(\alpha_i) \log(w_i) = 0 \quad (32)$$

(if we look for a first integral of the form $1 + \sum_{i=1}^{\infty} h_i(x, y)$ with $h_i(x, y)$ being homogeneous polynomials of the degree i) or

$$\sum_{i=1}^s \alpha_i k_i + \sum_{i=1}^s \mathcal{A}(\alpha_i) \log(w_i) = |a| - |b| \quad (33)$$

(if we look for a Lyapunov first integral $\Phi = xy + h.o.t.$).

Quadratic system

$$\begin{aligned} \mathcal{A}(W) := & a_{01}(|b|-1) \frac{\partial W}{\partial a_{01}} + a_{10}(1-|a|) \frac{\partial W}{\partial a_{10}} + a_{-12}(|a|+2|b|-3) \frac{\partial W}{\partial a_{-12}} + \\ & b_{01}(|b|-1) \frac{\partial W}{\partial b_{01}} + b_{10}(1-|a|) \frac{\partial W}{\partial b_{10}} + b_{2,-1}(-2|a|-|b|+3) \frac{\partial W}{\partial b_{2,-1}} \\ |a| = & a_{10} + a_{01} + a_{-12}, \quad |b| = b_{01} + b_{10} + b_{2,-1}. \end{aligned}$$

Quadratic system

$$\mathcal{A}(W) := a_{01}(|b|-1)\frac{\partial W}{\partial a_{01}} + a_{10}(1-|a|)\frac{\partial W}{\partial a_{10}} + a_{-12}(|a|+2|b|-3)\frac{\partial W}{\partial a_{-12}} + \\ b_{01}(|b|-1)\frac{\partial W}{\partial b_{01}} + b_{10}(1-|a|)\frac{\partial W}{\partial b_{10}} + b_{2,-1}(-2|a|-|b|+3)\frac{\partial W}{\partial b_{2,-1}}$$

$$|a| = a_{10} + a_{01} + a_{-12}, \quad |b| = b_{01} + b_{10} + b_{2,-1}.$$

Hamiltonian system: $\mathbf{V}(J_1)$, where $J_1 = \langle 2a_{10} - b_{10}, 2b_{01} - a_{01} \rangle \Rightarrow$

$$a_{01} = 2b_{01}, \quad b_{10} = 2a_{10}$$

$$\mathcal{A}(W) := a_{10}(1-|a|)\frac{\partial W}{\partial a_{10}} + a_{-12}(|a|+2|b|-3)\frac{\partial W}{\partial a_{-12}} + \\ b_{01}(|b|-1)\frac{\partial W}{\partial b_{01}} + b_{2,-1}(-2|a|-|b|+3)\frac{\partial W}{\partial b_{2,-1}}$$

$$H = -\left(xy - \frac{a_{-12}}{3}y^3 - \frac{b_{2,-1}}{3}x^3 - a_{10}x^2y - b_{01}xy^2\right)$$

$W = 1 - a_{-12}/3 - b_{2,-1}/3 - a_{10} - b_{01}$ is a solution to

$$\mathcal{A}(W) = W(|a| - |b|).$$

$\mathbf{V}(J_3)$, where $J_3 = \langle 2a_{01} + b_{01}, a_{10} + 2b_{10}, a_{01}b_{10} - a_{-12}b_{2,-1} \rangle$,

$$\left\{ \begin{array}{l} \mathcal{A}(W) := a_{01}(|b| - 1) \frac{\partial W}{\partial a_{01}} + a_{10}(1 - |a|) \frac{\partial W}{\partial a_{10}} + a_{-12}(|a| + 2|b| - 3) \frac{\partial W}{\partial a_{-12}} \\ + b_{01}(|b| - 1) \frac{\partial W}{\partial b_{01}} + b_{10}(1 - |a|) \frac{\partial W}{\partial b_{10}} + b_{2,-1}(-2|a| - |b| + 3) \frac{\partial W}{\partial b_{2,-1}} \\ = W(|a| + |b|) \\ 2a_{01} + b_{01} = a_{10} + 2b_{10} = a_{01}b_{10} - a_{-12}b_{2,-1} = 0 \end{array} \right.$$

\Rightarrow

$$\begin{aligned} \mathcal{A}(W) &:= a_{01}(|b| - 1) \frac{\partial W}{\partial a_{01}} + b_{10}(1 - |a|) \frac{\partial W}{\partial b_{10}} + b_{2,-1}(-|b| - 2|a| + 3) \frac{\partial W}{\partial b_{2,-1}} \\ &= W(|a| + |b|) \quad (34) \end{aligned}$$

$$\ell_1 = 1 + 2 b_{10} x - a_{01} b_{2,-1} x^2 + 2 a_{01} y + 2 a_{01} b_{10} x y - \frac{a_{01} b_{10}^2}{b_{2,-1}} y^2,$$

$$\begin{aligned} \ell_2 = & (2 b_{10} b_{2,-1}^2 + 6 b_{10}^2 b_{2,-1}^2 x + 3 b_{10}^3 b_{2,-1}^2 x^2 - 3 a_{01} b_{10} b_{2,-1}^3 x^2 - a_{01} b_{10}^2 b_{2,-1}^3 x^3 - \\ & 6 a_{01} b_{10} b_{2,-1}^2 y - 3 b_{10}^4 b_{2,-1} x y + 6 a_{01} b_{10}^2 b_{2,-1}^2 x y - 3 a_{01}^2 b_{2,-1}^3 x y + 3 a_{01} b_{10}^3 b_{2,-1}^2 y^2 - \\ & 3 a_{01}^2 b_{10} b_{2,-1}^3 x^2 y - 3 a_{01} b_{10}^3 b_{2,-1} y^2 + 3 a_{01}^2 b_{10} b_{2,-1}^2 y^2 - 3 a_{01} b_{10}^4 b_{2,-1} x y^2 + 3 a_{01}^2 b_{10}^2 b_{2,-1}^2 y^3 - \\ & a_{01} b_{10}^5 y^3 - a_{01}^2 b_{10}^3 b_{2,-1} y^3) / (2 b_{10} b_{2,-1}^2) \end{aligned}$$

with the cofactors $k_1 = 2(b_{10}x - a_{01}y)$ and $k_2 = 3(b_{10}x - a_{01}y)$.

First integral

$$\Psi = \ell_1^{-3} \ell_2^2 \equiv c.$$

$$\begin{aligned}
L_1 &= 1 + 2a_{01} + 2b_{10} + 2a_{01}b_{10} - (a_{01}b_{10}^2)/b_{2,-1} - a_{01}b_{2,-1} \\
L_2 &= (a_{01}b_{10}^5 - 3a_{01}b_{10}^3b_{2,-1} - a_{01}^2b_{10}^3b_{2,-1} - 3b_{10}^4b_{2,-1} - \\
&3a_{01}b_{10}^4b_{2,-1} + 2b_{10}b_{2,-1}^2 + 6a_{01}b_{10}b_{2,-1}^2 + 3a_{01}^2b_{10}b_{2,-1}^2 + 6b_{10}^2b_{2,-1}^2 + \\
&6a_{01}b_{10}^2b_{2,-1}^2 + 3a_{01}^2b_{10}^2b_{2,-1}^2 + 3b_{10}^3b_{2,-1}^2 + 3a_{01}b_{10}^3b_{2,-1}^2 - 3a_{01}^2b_{2,-1}^3 - \\
&3a_{01}b_{10}b_{2,-1}^3 - 3a_{01}^2b_{10}b_{2,-1}^3 - a_{01}b_{10}^2b_{2,-1}^3 + a_{01}^2b_{2,-1}^4)/(2b_{10}b_{2,-1}^2)
\end{aligned}$$

$$\mathcal{A}(L_1) = K_1L_1, \quad \mathcal{A}(L_2) = K_2L_2,$$

$$\begin{aligned}
K_1 &= -2(a_{01} - b_{10}), \quad K_2 = -3(a_{01} - b_{10}), \\
U &= L_1^{-3}L_2^2 \text{ is a solution to } \mathcal{A}(U) = 0
\end{aligned}$$

$$W = \frac{U - 1}{-6a_{01}b_{10} - (3b_{10}^3)/b_{2,-1} - (3a_{01}^2b_{2,-1})/b_{10}}$$

is a solution to

$$\mathcal{A}(W) = W(|a| + |b|).$$

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Thank you for your attention!