# BSS Machines: Computability without Search Procedures 

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Some of this work is joint with Wesley Calvert.

## Turing-Computable Fields

Defn.: A computable field $F$ is a field with domain $\omega$, in which the field operations + and $\cdot$ are (Turing-) computable.

One considers the root set and the splitting set:

$$
\begin{gathered}
R_{F}=\{p \in F[X]:(\exists a \in F) p(a)=0\} \\
S_{F}=\{p \in F[X]: p \text { factors properly in } F[X]\} .
\end{gathered}
$$

From these sets, one can find the irreducible factors, hence the roots, of any $p \in F[X]$. Finding roots or factors requires only a simple search procedure, provided that they do exist.


The baby bird could not fly.


But he could walk. "Now I will go and find my mother," he said.




The computability theorist said to the steam shovel, "Are you a proof of the Riemann Hypothesis?"

The steam shovel said, "SNORT!"

## BSS Computability

Defn.: A BSS-machine has an infinite tape, indexed by $\omega$. At each stage, cofinitely many cells are blank, and finitely many contain one real number each. In a single step, the machine can copy one cell into another, or perform a field operation (,,$+- \cdot$, or $\div$ ) on two cells, or compare any cell to 0 (using $<$ or $=$ ) and fork, or halt.

The machine starts with a tuple $\vec{p} \in \mathbb{R}^{<\omega}$ of real parameters in its cells, and the input consists of a tuple $\vec{x} \in \mathbb{R}^{<\omega}$, written in the cells immediately following $\vec{p}$. The machine runs according to a finite program, and if it halts within finitely many steps, the output is the tuple of reals in the cells when it halts.

## BSS-Semidecidability

Defn.: A set $S \subseteq \mathbb{R}$ is:

- BSS-decidable if $\chi_{S}$ is BSS-computable;
- BSS-enumerable if $S$ is the image of $\omega(\subseteq \mathbb{R})$ under some partial BSS-computable function;
- BSS-semidecidable if $S$ is the domain of such a function.

So
$\{$ BSS-decidable sets $\} \subseteq\{$ BSS-semidecidable sets $\}$ and
$\{$ BSS-enumerable sets $\} \subseteq\{$ BSS-semidecidable $\}$. However, the set $\mathbb{A}$ of algebraic real numbers is BSS-semidecidable, but turns out not to be BSS-enumerable, nor BSS-decidable. Indeed, $\mathbb{Q}$ is not BSS-decidable. And there exist countable BSS-decidable sets which are not
BSS-enumerable. (Proofs by Herman-Isard, Meer, Ziegler.)

## Field Questions on $\mathbb{R}$

Lemma (Folklore): The splitting set $S_{\mathbb{R}}$ and the root set $R_{\mathbb{R}}$ are both BSS-decidable. Also, the number of real roots of $r \in \mathbb{R}[X]$ is BSS-computable.

Lemma: If $f: \mathbb{R}^{m} \rightarrow \mathbb{R}^{n}$ is BSS-computable by a machine with real parameters $\vec{p}$, then for all $\vec{x} \in \mathbb{R}^{m}, f(\vec{x})$ lies in the field $\mathbb{Q}(\vec{x}, \vec{p})$.

Corollary: $\mathbb{A}$ is not BSS-enumerable. Indeed, every BSS-enumerable set is contained in a finitely generated extension of $\mathbb{Q}$.

Corollary: No BSS-computable function can accept all inputs $q \in \mathbb{Q}[X]$ and output the real roots of each input $q$. (Hence neither can it output the irreducible factors of $q$ in $\mathbb{R}[X]$.)

Intuition: finding roots of a polynomial requires an AYMM search.

## Alternative Proof

Prop.: Neither $\mathbb{Q}$ nor $\mathbb{A}$ is BSS-decidable.
Proof: Suppose some BSS machine $M$ computes a total function $H: \mathbb{R} \rightarrow \mathbb{R}$, using real parameters $\vec{p}$. Choose an input $y \in \mathbb{R}$ transcendental over $\mathbb{Q}(\vec{p})$, and run $M$ on $y$. At each stage $s$, the $n$-th cell contains $f_{n, s}(y)$, for some $f_{n, s} \in \mathbb{Q}(\vec{p})(Y)$. Then there exists $\epsilon>0$ such that when $|x-y|<\epsilon$, each step by $M$ on input $x$ is identical to the computation on $y$, with $f_{n, s}(x)$ in place of $f_{n, s}(y)$ in the $n$-th cell. So, on the $\epsilon$-ball around $y, M$ computes a $\mathbb{Q}(\vec{p})$-rational function of its input. We say that $M$ computes a function which is locally $\mathbb{Q}(\vec{p})$-rational at transcendentals over $\vec{p}$.

If $M$ computes the characteristic function of $S \subseteq \mathbb{R}$, then it must be constant on such $\epsilon$-balls. So either $S$ or $\bar{S}$ is not dense in $\mathbb{R}$.

## Application to Finding Roots

Suppose that $M$, on every input $\left\langle a_{0}, \ldots, a_{4}\right\rangle$, outputs a real root of $X^{5}+a_{4} X^{4}+\cdots+a_{1} X+a_{0}$. Choosing $\vec{a} \in \mathbb{R}^{5}$ algebraically independent over the parameters $\vec{p}$ of $M$, we would have a rational function over $\mathbb{Q}(\vec{p})$ which gives a root of each monic degree-5 polynomial in $\mathbb{R}[X]$ with coefficients within $\epsilon$ of $\vec{a}$. But then this rational function extends from this open $\epsilon$-ball to give a general formula for such a root. By the Ruffini-Abel Theorem, this is impossible.

The same would hold even for BSS machines enhanced with the ability to find $n$-th roots of positive real numbers.

## Algebraic Numbers of Degree $d$

Defn.: $\mathbb{A}_{d}$ is the set of all algebraic real numbers of degree $\leq d$ over $\mathbb{Q} . \mathbb{A}_{=d}$ is the set $\left(\mathbb{A}_{d}-\mathbb{A}_{d-1}\right)$.

Question (Meer-Ziegler): Can a BSS machine with oracle $\mathbb{A}_{d}$ decide the set $\mathbb{A}_{d+1}$ ?

Answer (work in progress): No. So we have

$$
\mathbb{Q}=\mathbb{A}_{1} \prec_{B S S} \mathbb{A}_{2} \prec_{B S S} \mathbb{A}_{3} \prec_{B S S} \cdots \prec_{B S S} \mathbb{A} .
$$

## Proving $\mathbb{A}_{d+1} \npreceq \mathbb{A}_{d}$

A process similar to before: If $M$ with parameters $\vec{p}$ is an oracle BSS-machine deciding $\mathbb{A}_{d+1}$ from oracle $\mathbb{A}_{d}$, let $y$ be transcendental over $\mathbb{Q}(\vec{p})$. Then $M^{\mathbb{A}_{d}}$ on input $y$ halts and outputs 0 , with finitely many $f \in \mathbb{Q}(\vec{p})(Y)$ giving the values in its cells during the computation. We claim that $\exists x \in \mathbb{A}_{d+1}$ sufficiently close to $y$ that $M^{\mathbb{A}_{d}}$ on input $x$ mirrors this computation and also outputs 0 .

Let $F$ be the set of nonconstant $f(Y)$ used.
Problem: we need to ensure $f(x) \notin \mathbb{A}_{d}$ for every $f \in F$.

## Getting all $f(x) \notin \mathbb{A}_{d}$

- We may ignore any $f \in F$ in which a transcendental parameter $p_{i}$ appears. So assume there is a single algebraic parameter $p$.
- If $f(x)=a \in \mathbb{A}_{d}$, and $f(X)=\frac{g(X)}{h(X)}$ with $g, h \in \mathbb{Q}(p)[X]$, then $x$ is a root of $f_{a}(X)=g(X)-a h(X) \in \mathbb{A}_{d}(p)[X]$. Make sure that the minimal polynomial $q(X)$ of $x$ over $\mathbb{Q}$ stays irreducible in $\mathbb{A}_{d}(p)[X]$, so that if $f(x)=a$, then $q(X)$ would divide $f_{a}(X)$.
- We can choose such $q(X)$ so that $q(X)$ does not divide any $f_{a}(X)$ with $a \in \mathbb{A}_{d}$ and $f \in F$. Indeed, with all other coefficients fixed, there are only finitely many constant terms $q_{0}$ which would allow $q$ to divide any $f_{a}$.
- Choose $q_{0}$ so that $q(X)$ has a real root $x$ within $\epsilon$ of $y$.


## Summary

For the root $x$ of $q(X)$ chosen above, we have $x \in \mathbb{A}_{d+1}$. Since $|x-y|<\epsilon$, we know that for all nonconstant $f \in F, f(x)$ and $f(y)$ have the same sign, with $f(x) \notin \mathbb{A}_{d}$ and $f(y) \notin \mathbb{A}_{d}$. So the computation by the BSS machine $M$ on input $x$ parallels that on input $y$, and both halt (at the same step) and output 0 . Thus $M^{\mathbb{A}_{d}}$ does not decide the set $\mathbb{A}_{d+1}$.

## More General Questions

- What other AYMM searches can be investigated by translating them into problems in $\mathbb{R}$ and trying to compute them using BSS machines?
- Can one do anything similar with Infinite Time Turing Machines?
- Is there any way to consider AYMM searches for Gödel numbers of proofs?

