

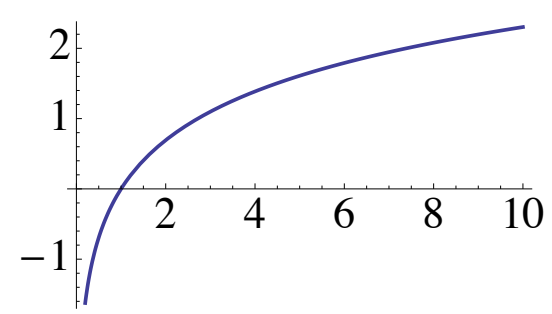
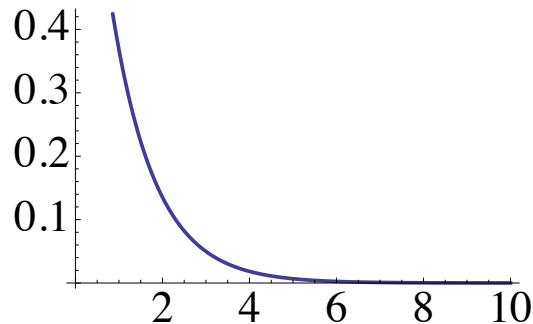
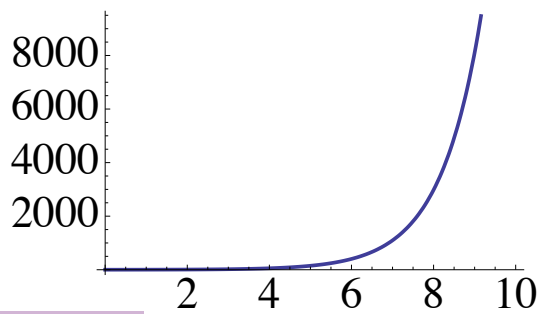
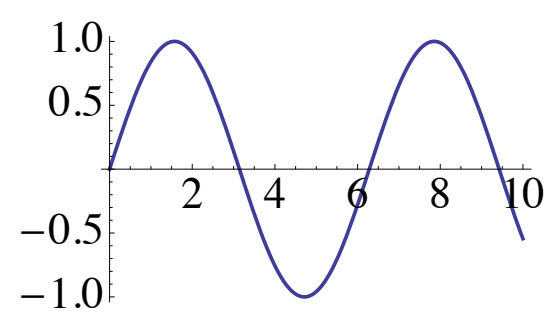
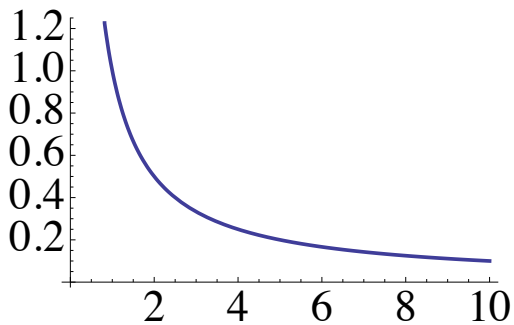
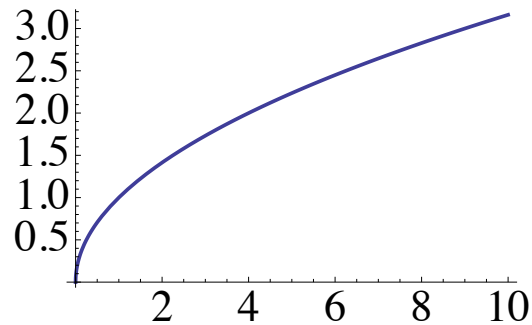
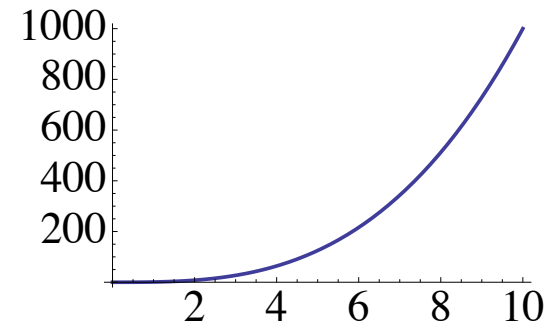
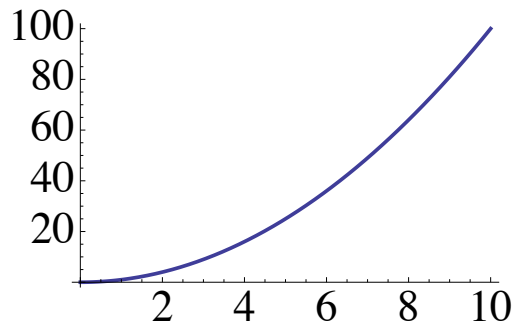
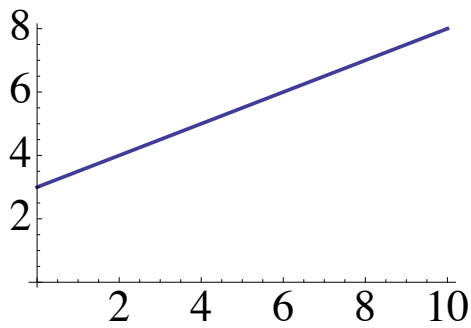
# The next few days

**Goals:** Understand function fitting, introduce *Mathematica*

## Frame of reference:

- ▶ **Formulation.** Suppose the problem has been properly formulated.
  - ▶ Problem statement is precise and clear, simplifying assumptions.
  - ▶ Dependent variable(s) and independent variable determined.
- ▶ Now we need a mathematical model; one type is a function.
  - ▶ We collect data\*, plot it, and notice a pattern.  $y \approx Cx^k$  ???
  - ▶ **Simplifying assumption:** The independent variable is a (simple) function of the dependent variables.
- ▶ **Math. Manipulation.** Determine the best function of this type.
  - ▶ **Now:** Visually.                      **Later:** Using a computer
- ▶ **Evaluation.** Does this function fit the data well?
- ▶ More evaluation: Determine errors, evaluation criteria...

# Functions you should recognize on sight



Think  
Pair  
Share

What are these functions?

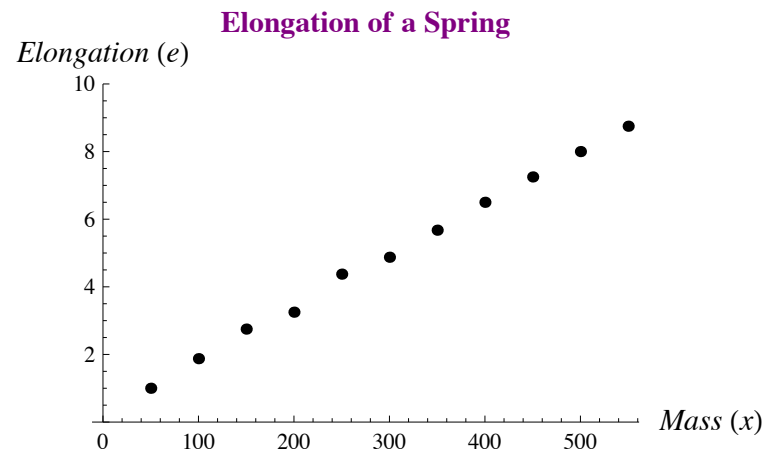
What is the most general equation of each type?

# Springs and Elongations

## Example: Modeling Spring Elongation

Take your favorite spring. Attach different masses.  
How much does it stretch from rest? [Its **elongation.**]

When we plot the data, we get the following **scatterplot.**



mass	elong
$x$	$y$
50	1.000
100	1.875
150	2.750
200	3.250
250	4.375
300	4.875
350	5.675
400	6.500
450	7.250
500	8.000
550	8.750

What do you notice? \_\_\_\_\_

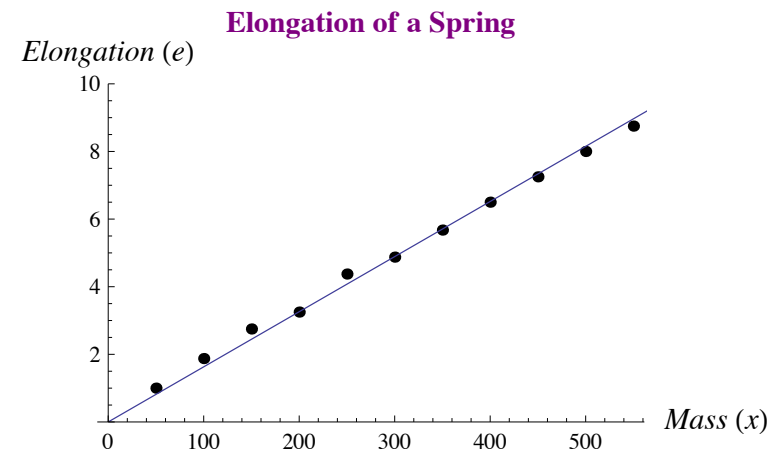
# Proportionality

When data seems to lie on a line through the origin, we expect the two variables to be **proportional**; in this case,  $y = kx$  for some constant  $k$ .

We need to find this **constant of proportionality**  $k$ .

So: Estimate the slope of the line. **How?**

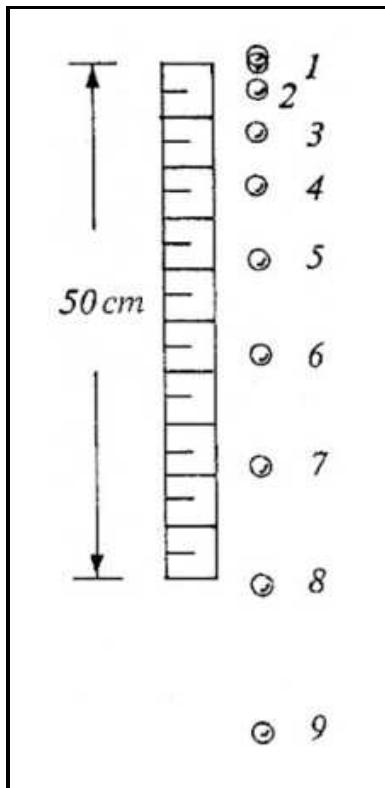
## 1. Guesstimating



## 2. Mathematically: **Linear Regression / Least Squares** (For another day)

# Fitting Gravity Data

## Example. Modeling the dropping of a golf ball



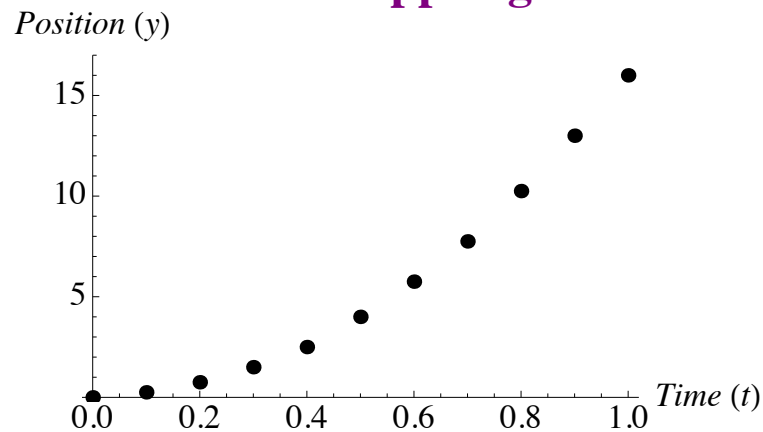
Source:  
practicalphysics.org

Let's use an experiment to test the gravity model from last time.

Use a camera to record the position every tenth of a second.

Data would be similar to the table →  
It's plotted in the scatterplot below.

### Position of a dropped golf ball



$t$	$y$
0.0	0.00
0.1	0.25
0.2	0.75
0.3	1.50
0.4	2.50
0.5	4.00
0.6	5.75
0.7	7.75
0.8	10.25
0.9	13.00
1.0	16.00

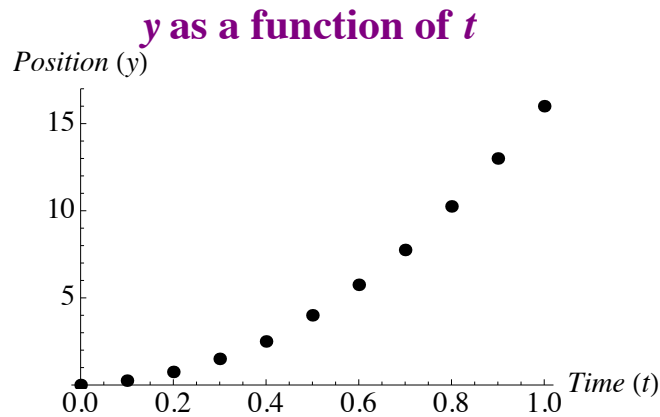
[Ignore data on p. 25.]  
[It's BAD data.]

# Fitting Gravity Data

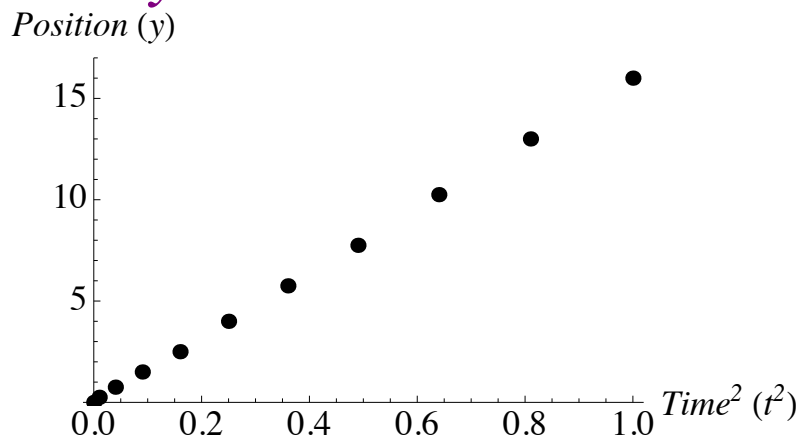
These data seem to fit a                     . How can we be sure?

1. Plot distance as a function of  $t^2$ .

Next, estimate the constant of proportionality.



*y as a function of  $t^2$*



This implies  
 $y \approx \underline{\hspace{1cm}} t^2$ .

$t$	$t^2$	$y$
0.0		0.00
0.1		0.25
0.2		0.75
0.3		1.50
0.4		2.50
0.5		4.00
0.6		5.75
0.7		7.75
0.8		10.25
0.9		13.00
1.0		16.00

# Fitting Gravity Data

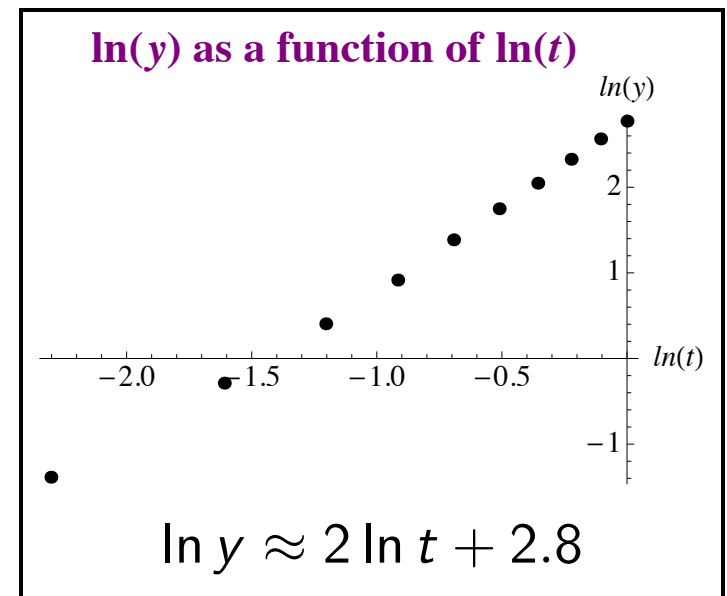
**Key Concept:** When fitting data to a function  $y = Ct^k$ ,  
An alternate method is:

2. ★ Plot the log of distance as a function of log of time. ★

▶ WHY? Suppose  $y = Ct^k$ . Taking a logarithm of both sides,  
 $\ln y = \ln(Ct^k) =$

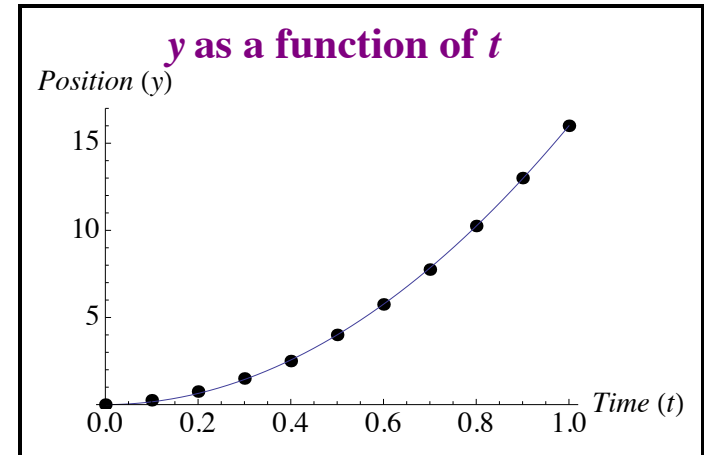
**Conclusion:** To approximate  $C$  and  $k$ ,

- ▶ First, calculate  $\ln y$  and  $\ln t$  for each datapoint.
- ▶ Fit the transformed data to a line.
  - ▶ The slope is an approximation for  $k$ .
  - ▶ The  $y$ -intercept approximates  $\ln C$ .



# Fitting Gravity Data

We have determined that our gravity model  
$$y(t) = 16t^2$$
appears to model the dropping of a golf ball.



**Example.** Raindrops—Our model gives their position as  $y(t) = 16t^2$ .

A raindrop falling from 1024 feet would land after  $t = 8$  seconds.

However, an experiment shows that the fastest drop takes 40 seconds, and that drops fall at different rates depending on their size.

Even if we have a good model for one situation doesn't mean it will apply everywhere. **We always need to question our assumptions.**

—Extensive gravity discussion in Section 1.3.—



# Modeling Population Growth

**Example.** Modeling the size of a population.

We would like to build a **simple** model to predict the size of a population in 10 years.

► A very **macro**-level question.

**Definitions:** Let  $t$  be time in years;  $t = 0$  now.

$P(t)$  = size of population at time  $t$ .

$B(t)$  = number of births between times  $t$  and  $t + 1$ .

$D(t)$  = number of deaths between times  $t$  and  $t + 1$ .

Therefore,  $P(t + 1) = \underline{\hspace{10em}}$ .

Definitions  
imply

$$P(4) =$$

$$B\left(\frac{1}{2}\right) =$$

$$B(5) - D(5)$$

$$=$$

**Assumption:** The birth rate and death rate stay constant.

That is, the birth rate  $b = \frac{B(t)}{P(t)}$  and death rate  $d = \frac{D(t)}{P(t)}$  are constants.

**Assumption:** No migration.

# Population Growth

Therefore, 
$$P(t + 1) = P(t) \left[ \frac{P(t)}{P(t)} + \frac{B(t)}{P(t)} - \frac{D(t)}{P(t)} \right].$$

Under our assumptions, 
$$P(t + 1) = P(t)[1 + b - d].$$

This implies:  $P(1) = \underline{\hspace{2cm}},$   
 $P(2) = \underline{\hspace{2cm}}, \dots$

In general,  $P(n) = \underline{\hspace{2cm}}.$

**Definition.** The **growth rate** of a population is  $r = (1 + b - d)$ .  
 This constant is also called the **Malthusian parameter**.

A model for the size of a population is

$$P(t) = P(0)r^t,$$

where  $P(0)$  and  $r$  are constants.

# Applying the Malthusian Model

Approximate US Population at: <http://www.census.gov/popclock/>

**Example 1.** Suppose that the current US population is 323,090,000. Assume that the birth rate is 0.02 and the death rate is 0.01. What will the population be in 10 years?

**Answer.** Use  $P(t) = P(0)r^t$ :

**Refinement.** [Approx. US Growth Rate at http://www.wolframalpha.com/input/?i=US+birth+rate](http://www.wolframalpha.com/input/?i=US+birth+rate)

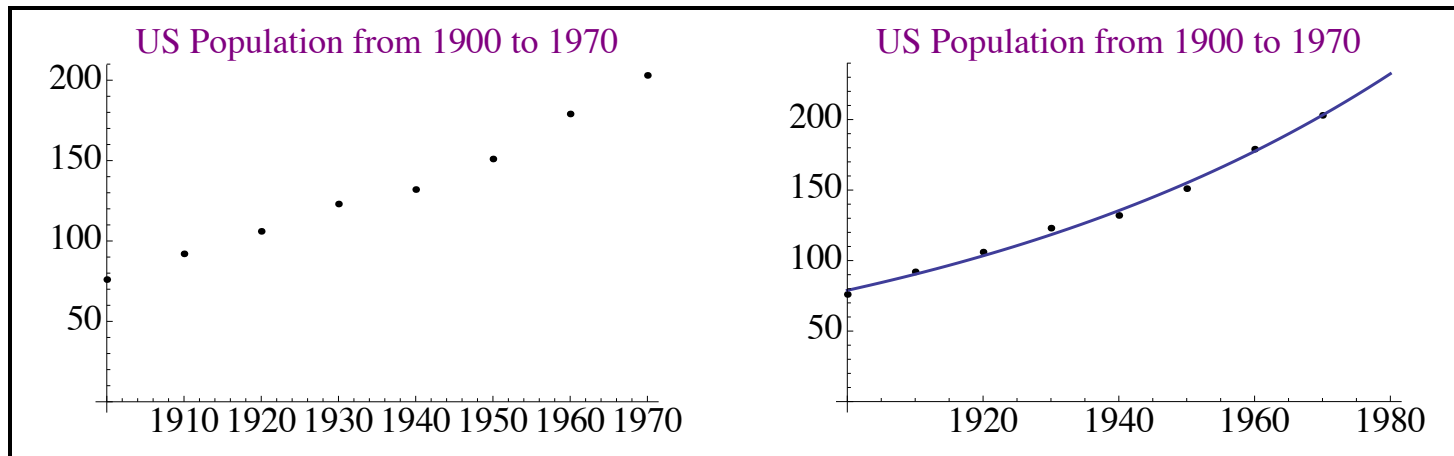
**Resource:** Wolfram Alpha, integrable directly into *Mathematica*.

**Example 2.** How long will it take the population to double?

**Answer.** Use  $P(t) = P(0)r^t$ :

# Determining constants of exponential growth

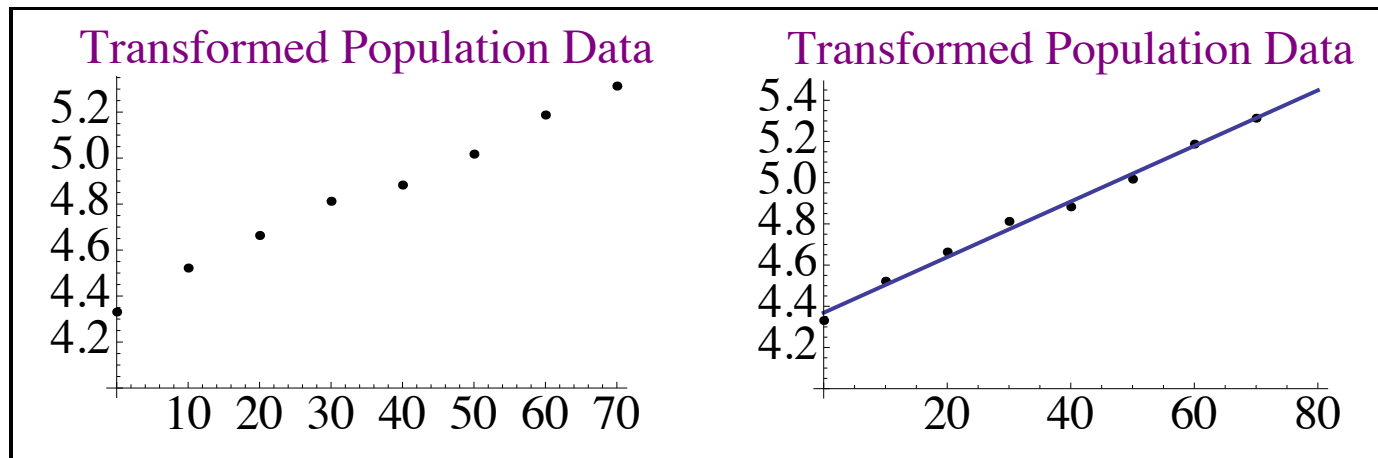
**Goal:** Given population data, determine model constants.



- ▶ Take the logarithm of both sides of  $P(t) = P(0)r^t$ .
- ▶ We have  $\ln[P(t)] = \underline{\hspace{4cm}}$ .
- ▶ A linear fit for  $P(t)$  vs.  $t$  gives values for  $\underline{\hspace{2cm}}$  and  $\underline{\hspace{2cm}}$ .
- ▶ Exponentiate each value to find the values for  $P(0)$  and  $r$ .

# Determining constants of exponential growth

Here we plot  $\ln[P(t)]$  as a function of  $t$ :



The line of best fit is approximately  $\ln[P(t)] = 4.4 + 0.0135t$ .

Therefore our model says  $P(t) \approx e^{4.4} (e^{0.0135})^t = 81.5 \cdot (1.014)^t$ .

**Analysis:** ► History indicates we should split the interval [1900, 1970].

► We have to be careful when trying to **extrapolate!**

★ **Important:** Transformations distort distances between points, so verification of a fit should always take place on y versus x axes. ★

# Residuals

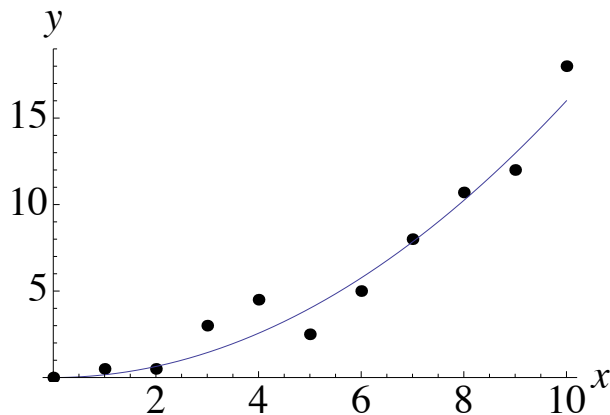
Once you determine a function of best fit, then you should verify that it fits well. One way to do this is to look at the residual plot.

*Definition:* Given a point  $(x_i, y_i)$  and a function fit  $f(x)$ , the **residual**  $r_i$  is the error between the actual and predicted values.

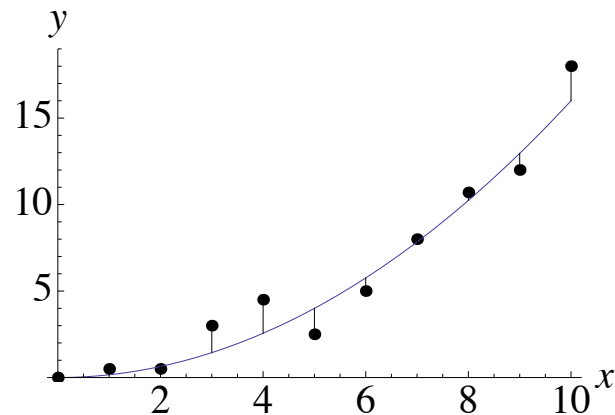
Mathematically,  $r_i = y_i - f(x_i)$ .

*Definition:* A **residual plot** is a plot of the points  $(x_i, r_i)$ .

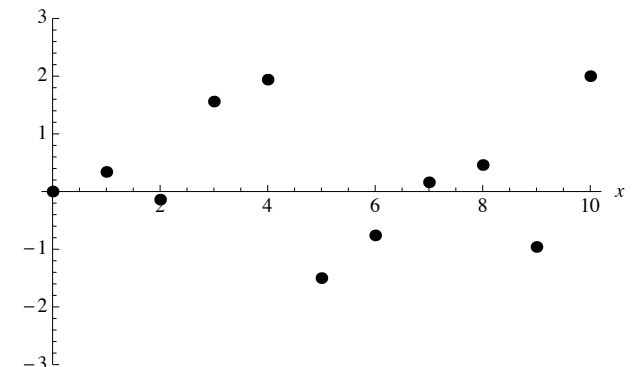
**Data Plot with Function Fit**



**Residuals Shown**



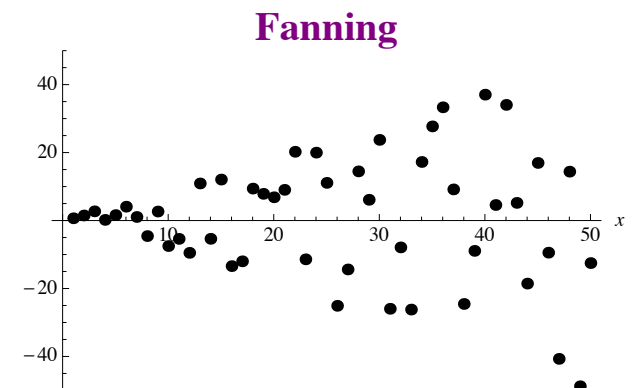
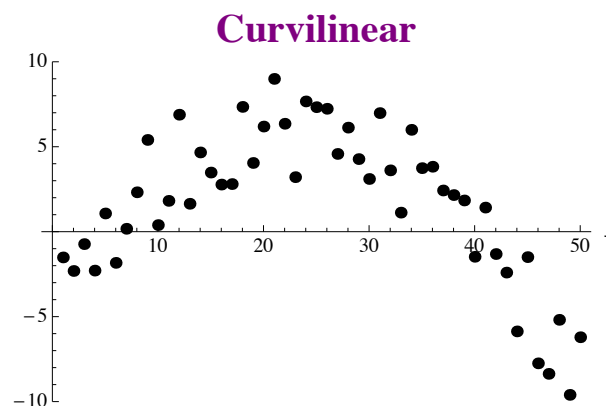
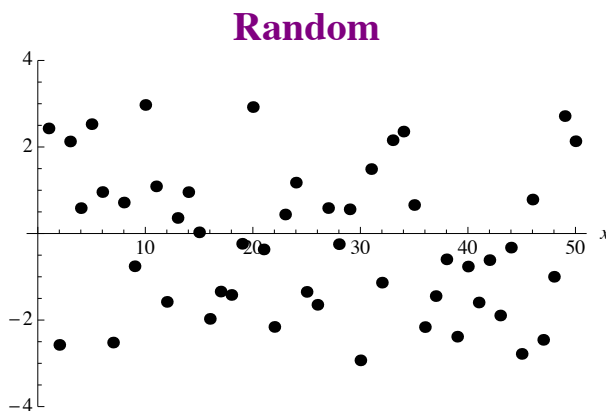
**Residual Plot**



# Residuals

The structure of the points in the residual plot give clues about whether the function fits the data well. Three common appearances:

1. **Random** : Residuals are randomly scattered at a consistent distance from axis. Indicates a good fit, as on previous page.
2. **Curvilinear**: Residuals appear to follow a pattern. Indicates that some aspect of model behavior is not taken into account.
3. **Fanning**: Residuals small at first and get larger (or vice versa). Indicates non-constant variability (model better for small  $x$ ?).



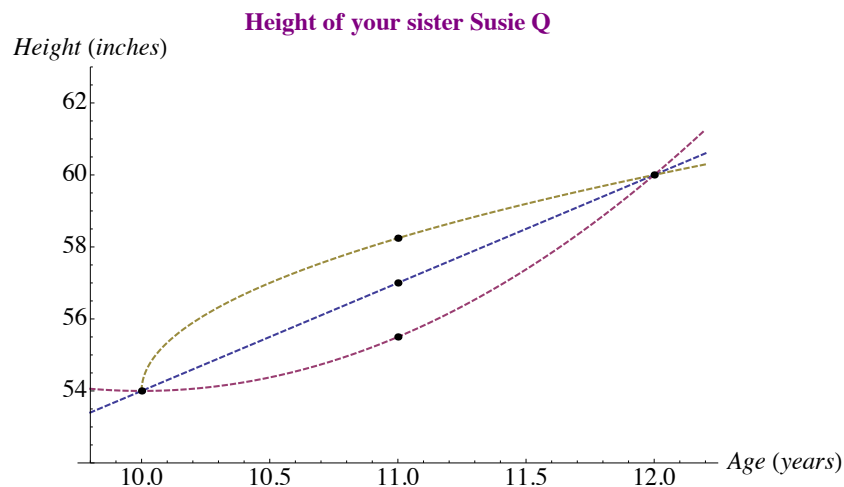
# Interpolation vs. Extrapolation

Suppose you have collected a set of *known* data points  $(x_i, y_i)$ , and you would like to estimate the  $y$ -value for an *unknown*  $x$ -value.

The name for such an estimation depends on the placement of the  $x$ -value relative to the *known*  $x$ -values.

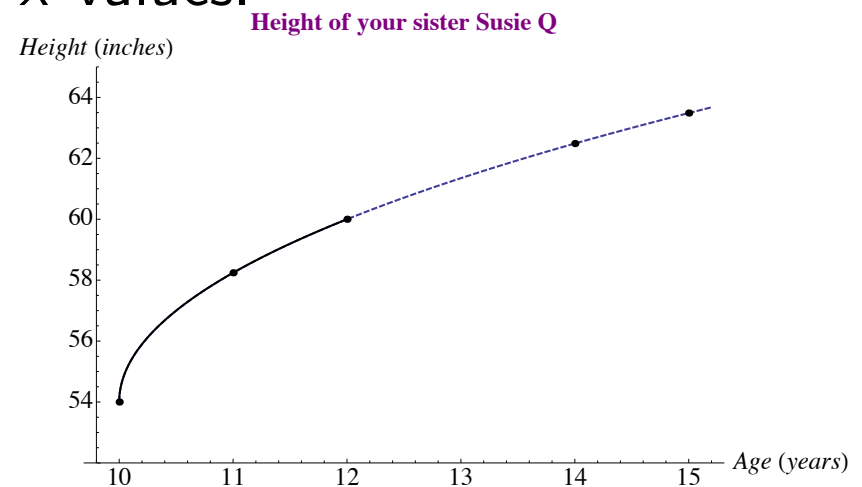
## Interpolation

Inserting one or more  $x$ -values between known  $x$ -values.



## Extrapolation

Inserting one or more  $x$ -values outside of the range of known  $x$ -values.





# Interpolation vs. Extrapolation

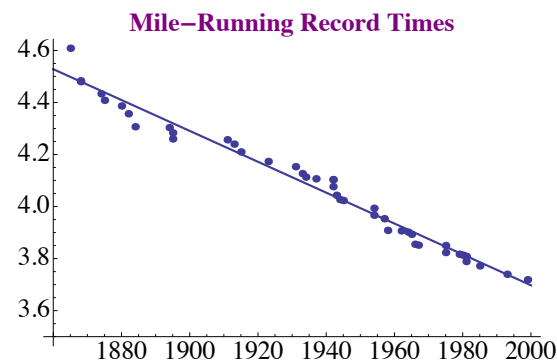
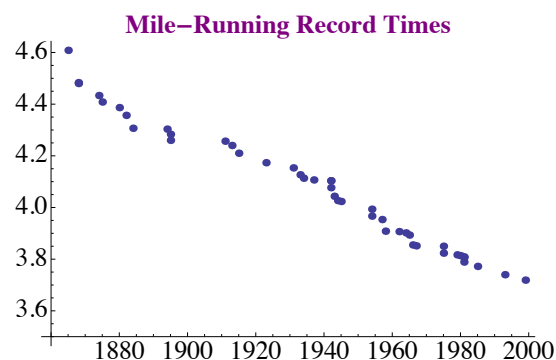
- ▶ The most common method for **interpolation** is taking a weighted average of the two nearest data points; suppose  $x_1 < x < x_2$ , then,

$$f(x) \approx y_1 + \frac{y_2 - y_1}{x_2 - x_1}(x - x_1).$$

- ▶ In both interpolation and extrapolation, when you have a function  $f$  that is a good fit to the data, simply plug in  $y = f(x)$ .
- ▶ Confidence in approximated values depends on confidence in your data and your model.
- ▶ Confidence in extrapolated data is higher when closer to the range of known  $x$ -values.

## Extrapolation: Running the Mile (p. 162)

Below is a plot of the years in which a record was broken for running a mile and the record-breaking time.



The data appears to fit the line  $T(t) = 15.5639 - 0.00593323t$ .

Solve for  $T(t) = 0$ : You get  $t \approx 2623$ .

*Conclusion:* In the year 2623, the record will be zero minutes!

- ▶ Note the lack of realistic assumptions behind the data.
- ▶ Always be careful when you extrapolate!