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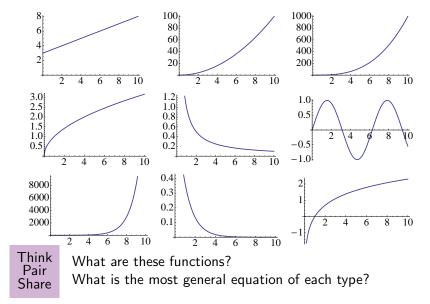
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- Evaluation. Does this function fit the data well?
- ▶ More evaluation: Determine errors, evaluation criteria...

Functions you should recognize on sight



Springs and Elongations

Example: Modeling Spring Elongation

Take your favorite spring. Attach different masses. How much does it stretch from rest? [Its **elongation**.]

Springs and Elongations

Example:	Modeling	Spring	Elongation

Take your favorite spring. Attach different masses.

How much does it stretch from rest? [Its **elongation**.]

When we plot the data, we get the following **scatterplot**.

	Elongation of a Spring	2
Elongation (e) 10		2
8	. • •	3
6	. • •	3
4	•	4
2	Mass (x)	4
0 10	0 200 300 400 500	5
What do you notice?		5

mass elong Χ 50 1.000 100 1.875

150 2.750 3.250

200 250 4.375

300 4.875 5.675 350 400 6.500

450 7.250 500 8.000

550

8.750

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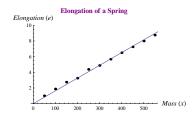
We need to find this **constant of proportionality** k.

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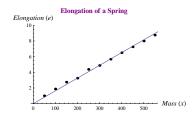
1. Guesstimating



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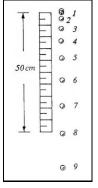
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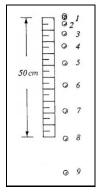
 Mathematically: Linear Regression / Least Squares (For another day)

Example. Modeling the dropping of a golf ball



Source: practical physics.org

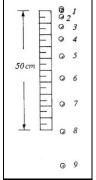
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Let's use an experiment to test the gravity model from last time.

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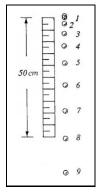


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Use a camera to record the position every tenth of a second.

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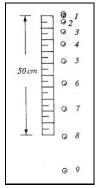
Use a camera to record the position every tenth of a second.

Data would be similar to the table \rightarrow

t	y
0.0	0.00
0.1	0.25
0.2	0.75
0.3	1.50
0.4	2.50
0.5	4.00
0.6	5.75
0.7	7.75
8.0	10.25
0.9	13.00
1.0	16.00

[Ignore data on p. 25.] [It's BAD data.]

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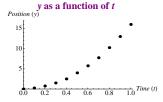
Data would be similar to the table \rightarrow It's plotted in the scatterplot below.

Pocit	ion o	f a dr	onne	d gol	f ball	
Position (ı a uı	oppe	u goi	ı van	
15					•	
-				•	•	
10				•		
			_	•		
5			•			
1.	. • . '	• •			Time (
0.0	0.2	0.4	0.6	0.8	1.0 Time (1)

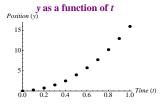
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These data seem to fit a $\frac{}{\text{(type of function)}}.$

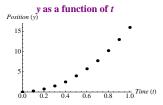


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15					•
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t	t^2	У
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,	,	t	t^2	У
y as a function of t Position (y)	-	0.0		0.00
15		0.1		0.25
10 · Con		0.2		0.75
10 tanks O _{III}		0.3		1.50
Time (t)		0.4		2.50
$0.0 0.2 0.4 0.6 0.8 1.0 1.0 1.0 y$ as a function of t^2		0.5		4.00
15		0.6		5.75
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y = 0.0 - 0.2 = 0.4 = 0.6 = 0.8 =	0.5		4.00
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This implies 10	0.7		7.75
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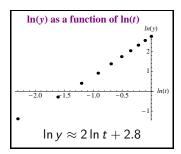
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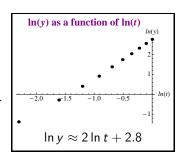


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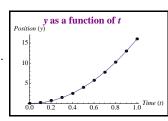
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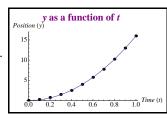
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 - ▶ The *y*-intercept approximates In *C*.



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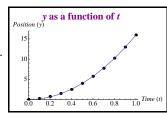


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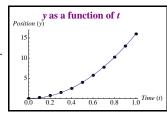
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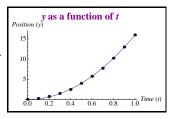


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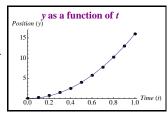
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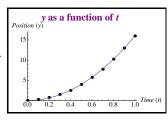
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Even if we have a good model for one situation doesn't mean it will apply everywhere. We always need to question our assumptions.

—Extensive gravity discussion in Section 1.3.—

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size of population at time t .

$$B(t) =$$
 number of births between times t and $t + 1$.

$$D(t) = \text{number of deaths between times } t \text{ and } t + 1.$$

Therefore,
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Definitions imply $P(4) = B(\frac{1}{2}) = B(5) - D(5)$

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Assumption: The birth rate and death rate stay constant.

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Assumption: No migration.

$$P(t+1) = P(t) \left[\frac{P(t)}{P(t)} + \frac{B(t)}{P(t)} - \frac{D(t)}{P(t)} \right].$$

$$P(t+1) = P(t)[1+b-d].$$

Therefore,
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A model for the size of a population is $P(t) = P(0)r^t$, where P(0) and r are constants.

Applying the Malthusian Model

Approximate US Population at: http://www.census.gov/popclock

Example 1. Suppose that the current US population is 323,090,000. Assume that the birth rate is 0.02 and the death rate is 0.01. What will the population be in 10 years?

Answer. Use $P(t) = P(0)r^t$:

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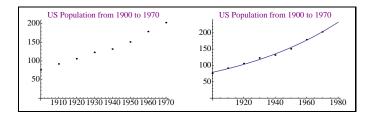
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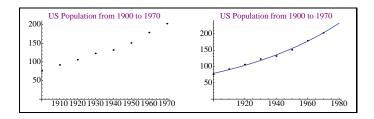
Refinement. (Approx. US Growth Rate at http://www.wolframalpha.com/input/?i=US+birth+rate

Resource: Wolfram Alpha, integrable directly into *Mathematica*.

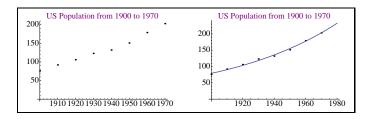
Example 2. How long will it take the population to double?

Answer. Use $P(t) = P(0)r^t$:

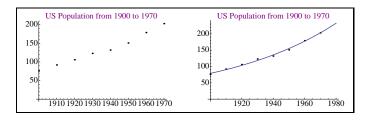




- ▶ Take the logarithm of both sides of $P(t) = P(0)r^t$.
- $\blacktriangleright \text{ We have } \ln[P(t)] = \underline{\hspace{1cm}}$

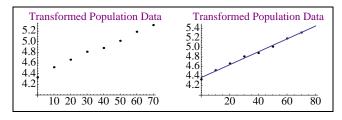


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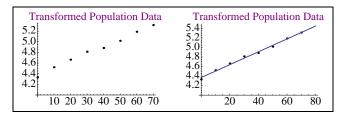


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- ightharpoonup A linear fit for P(t) vs. t gives values for and
- **Exponentiate** each value to find the values for P(0) and r.

Here we plot ln[P(t)] as a function of t:

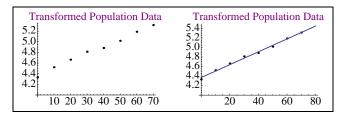


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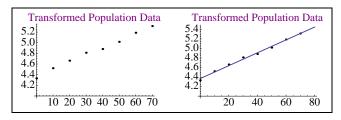
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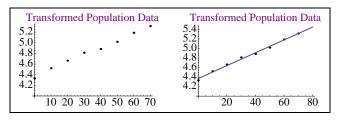


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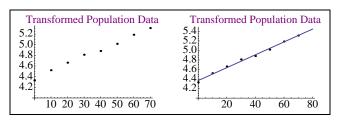
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- \star Important: Transformations distort distances between points, so verification of a fit should always take place on y versus x axes. \star

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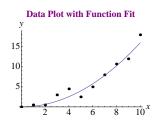
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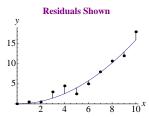
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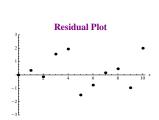
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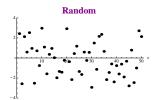




Residuals

The structure of the points in the residual plot give clues about whether the function fits the data well. Three common appearances:

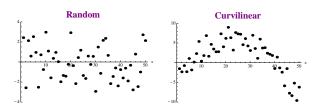
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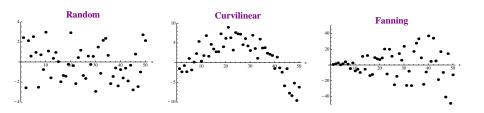
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- 3. **Fanning**: Residuals small at first and get larger (or vice versa). Indicates non-constant variability (model better for small x?).



Suppose you have collected a set of *known* data points (x_i, y_i) , and you would like to estimate the *y*-value for an *unknown x*-value.

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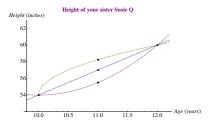
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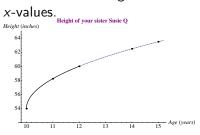
Interpolation

Inserting one or more *x*-values between known *x*-values.



Extrapolation

Inserting one or more *x*-values outside of the range of known



The most common method for interpolation is taking a weighted average of the two nearest data points; suppose $x_1 < x < x_2$, then, $f(x) \sim x_1 + y_2 - y_1$

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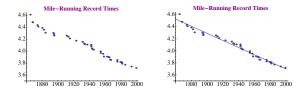
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- ► Confidence in extrapolated data is higher when closer to the range of known *x*-values.

Below is a plot of the years in which a record was broken for running a mile and the record-breaking time.

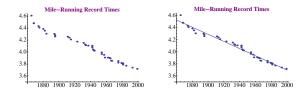


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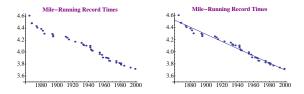
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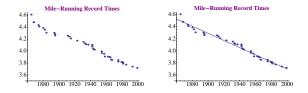
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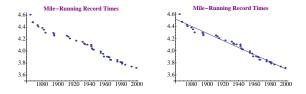
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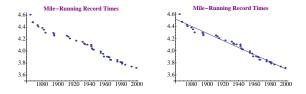


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- Always be careful when you extrapolate!