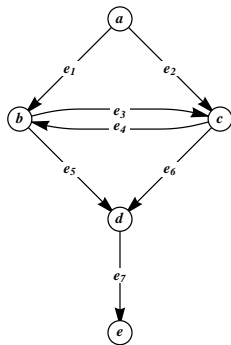


Directed Graphs

Definition. A **directed graph** (or **digraph**) is a graph $G = (V, E)$, where each edge $e = vw$ is directed from one vertex to another:

$$e : v \rightarrow w \quad \text{or} \quad e : w \rightarrow v.$$

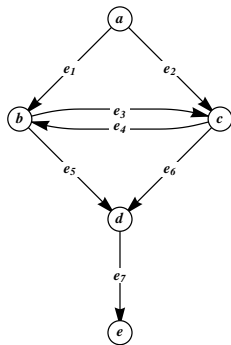


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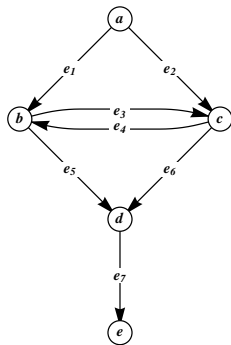
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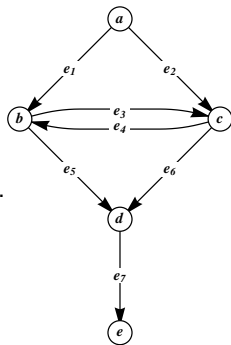
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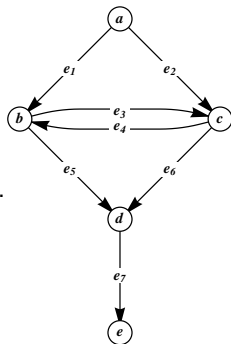
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Important. Any **path** or **cycle** in a digraph must respect the direction on each edge.



Network Flows

Definition. A **network** is a directed graph with additional structure:

Network Flows

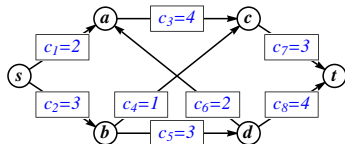
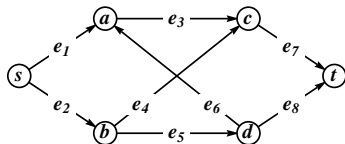
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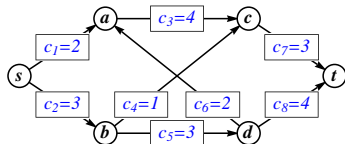
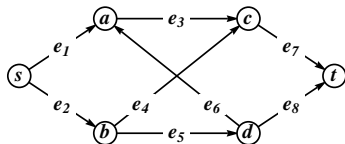
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Idea. Graph networks represent real-world networks such as traffic, water, communication, etc.

Goal: Send as much “stuff” from s to t while respecting capacities.

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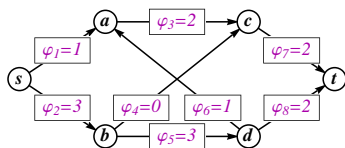
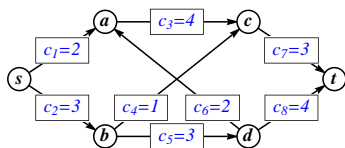
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- ▶ $\sum_{e \text{ into } v} \varphi_e = \sum_{e \text{ out of } v} \varphi_e$ for every vertex $v \in V(G)$ except s or t .
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Definition. When $\varphi_e = c_e$, we say that e is **saturated**, or **at capacity**.

Maximum Flow

Theorem. Given a flow $\vec{\varphi}$ on a network G , the net flow out of s is equal to the net flow into t . Symbolically,
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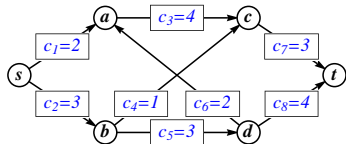
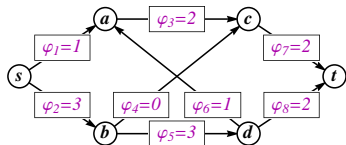
In G' , flow is now conserved at every vertex except possibly t . By Kirchhoff's Global Current Law (Theorem 6.2.2), flow must be conserved at t as well.

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Definition. The **throughput** or **value** of a flow $\vec{\varphi}$ is $\sum_{e \text{ out of } s} \varphi_e$, denoted $|\vec{\varphi}|$.

Idea: The throughput is the amount of “stuff” flowing through G .

In our example, $|\vec{\varphi}| = \underline{\hspace{2cm}}$.



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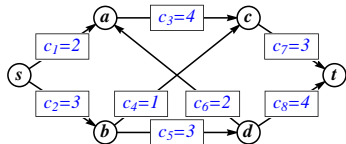
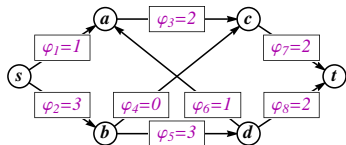
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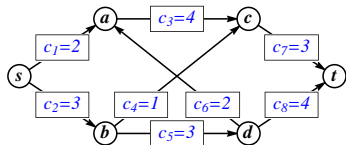
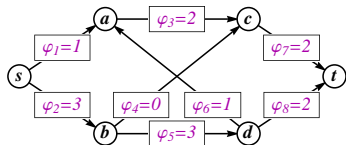
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MAX FLOW

maximize
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$|\vec{\varphi}|$

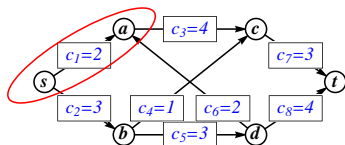
st-Cuts

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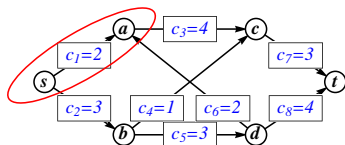
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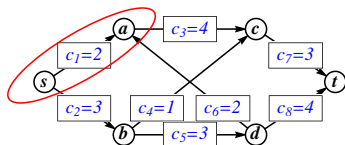
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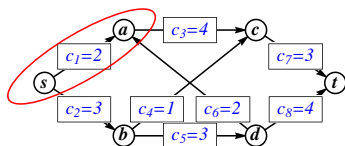
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★ Do **not** subtract the capacities of the edges going the other way. ★

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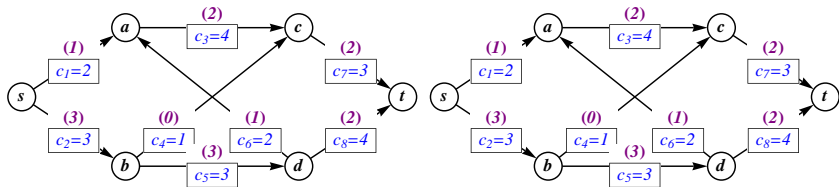
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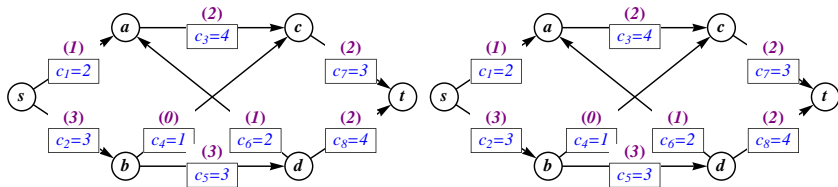
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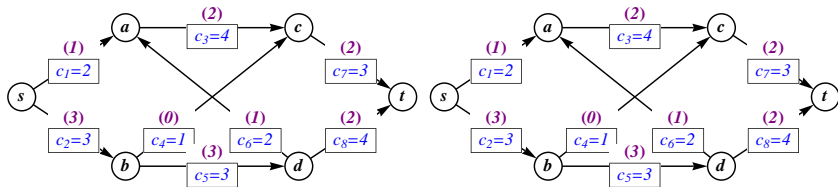
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We'll create a *companion graph* to keep track of augmenting paths.

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 - ▶ If $\varphi_e = 0$, orient the edge e **forward only**.
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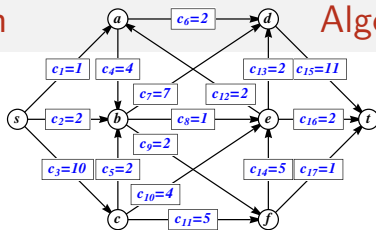
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 - ★ If there is no st -path in the flow companion graph, STOP.
 - Upon STOP, the current flow is a maximum flow. ←

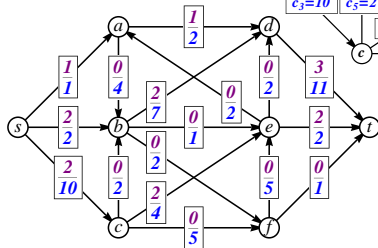
In addition, let X be the set of vertices reachable from s in the flow companion graph. Then $[X, X^c]$ is a minimum st -cut.

A Ford–Fulkerson

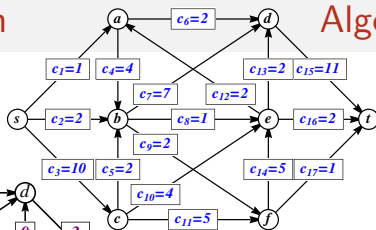
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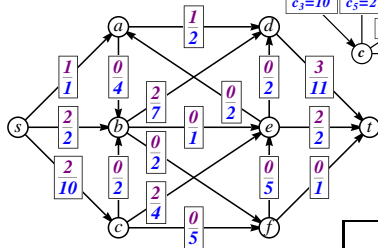
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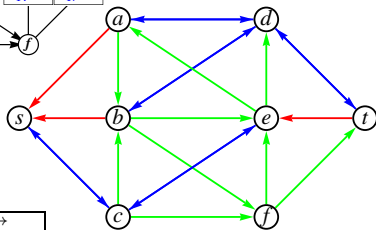
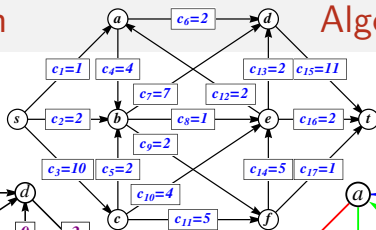


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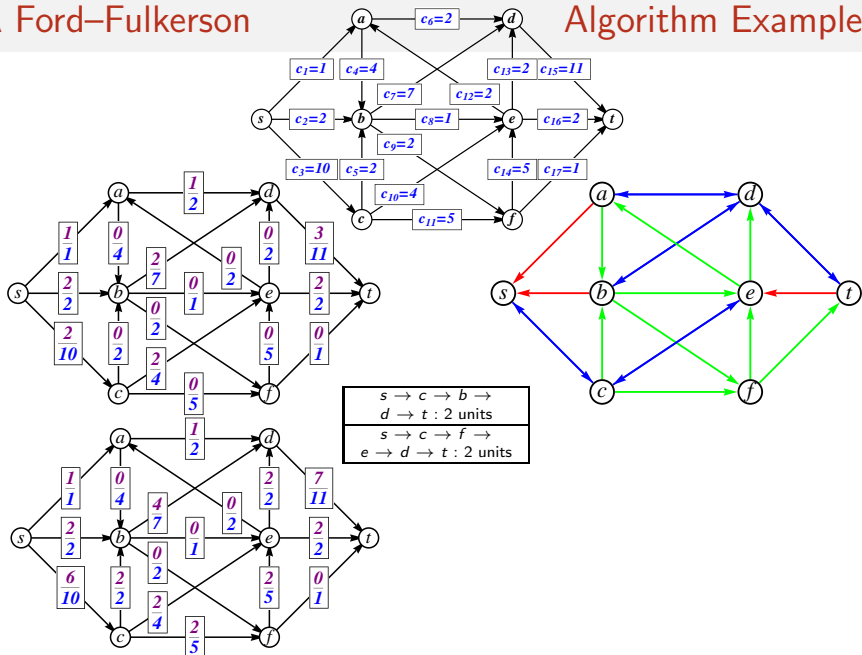
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$d \rightarrow t : 2 \text{ units}$
$s \rightarrow c \rightarrow f \rightarrow$
$e \rightarrow d \rightarrow t : 2 \text{ units}$

Algorithm Example

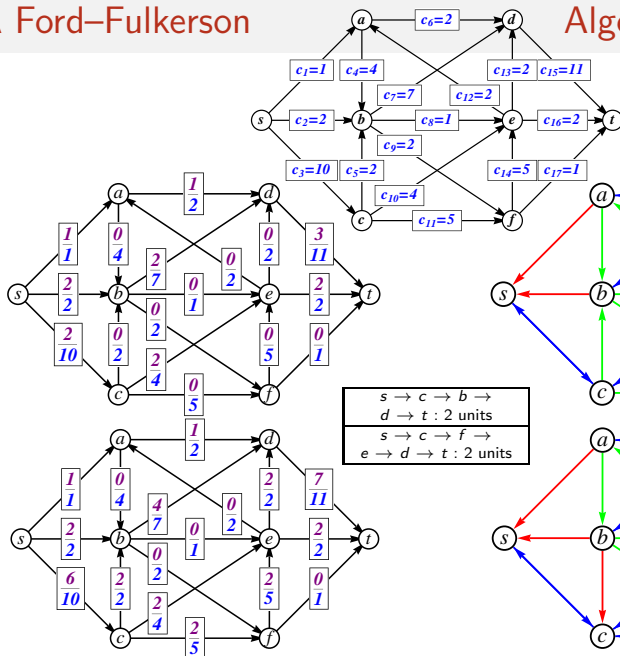


A Ford–Fulkerson

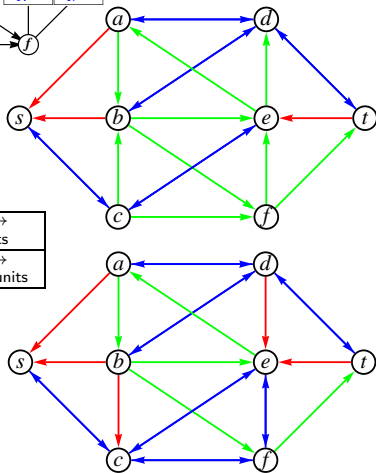
Algorithm Example



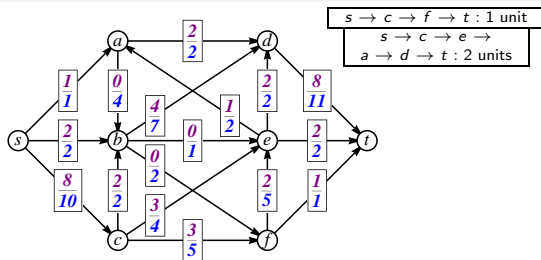
A Ford–Fulkerson



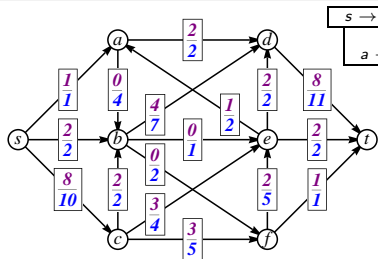
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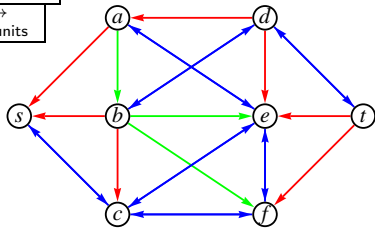
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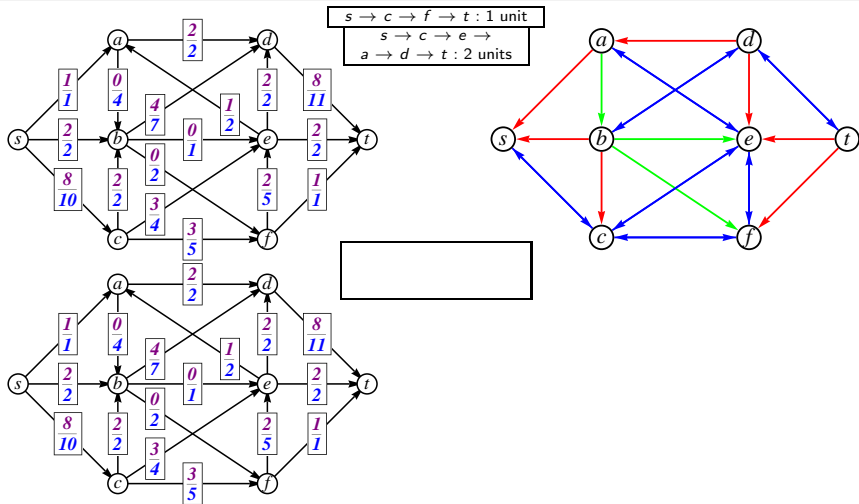
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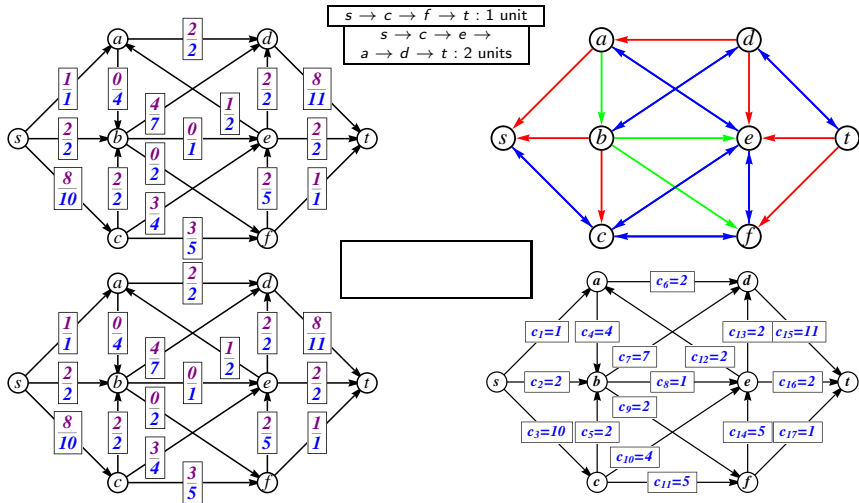
$s \rightarrow c \rightarrow f \rightarrow t$: 1 unit
 $s \rightarrow c \rightarrow e \rightarrow$
 $a \rightarrow d \rightarrow t$: 2 units



A Ford–Fulkerson Algorithm Example



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$X = \{ \underline{\hspace{2cm}} \}$, $[X, X^c] = \{ \underline{\hspace{2cm}} \}$, and $|[X, X^c]| = \underline{\hspace{2cm}}$.

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Conclusion. The flow is a max flow and the st -cut is a min cut.

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- ▶ When the capacities are integers, we always increase the throughput by integers. The algorithm does work when the capacities are not integers, but the proof is more involved.
- ▶ As presented here, this algorithm may be very slow.

