

Math 231 Practice Test 2 Solutions

1. (i)

$$\begin{aligned}\mathbf{u} \cdot (2\mathbf{u} - 3\mathbf{v}) &= (1, -1, 0, 2) \cdot ((2, -2, 0, 4) - (0, 0, 3, 15)) \\ &= (1, -1, 0, 2) \cdot (2, -2, -3, -11) \\ &= (1)(2) + (-1)(-2) + (0)(-3) + (2)(-11) \\ &= -18.\end{aligned}$$

(ii)

$$\|\mathbf{u} + \mathbf{v}\| = \|(1, -1, 1, 7)\| = \sqrt{1 + 1 + 1 + 49} = \sqrt{52}.$$

(iii) The vector $\mathbf{u} - \mathbf{v}$ has coordinates $(1, -1, -1, -3)$ and norm $\sqrt{12}$. Hence the unit vector in the direction of $\mathbf{u} - \mathbf{v}$ is the vector $\frac{1}{\sqrt{12}}(1, -1, -1, -3) = (\frac{1}{\sqrt{12}}, \frac{-1}{\sqrt{12}}, \frac{-1}{\sqrt{12}}, \frac{-3}{\sqrt{12}})$.

(iv) The distance between \mathbf{u} and \mathbf{v} is $\|\mathbf{u} - \mathbf{v}\| = \sqrt{12}$.

(v)

$$\begin{aligned}\mathbf{u} \text{ orthogonal to } \mathbf{u} + a\mathbf{v} &\iff \mathbf{u} \cdot (\mathbf{u} + a\mathbf{v}) = 0 \\ &\iff (1, -1, 0, 2) \cdot (1, -1, a, 2 + 5a) = 0 \\ &\iff (1)(1) + (-1)(-1) + (0)(a) + (2)(2 + 5a) = 0 \\ &\iff 6 + 10a = 0 \\ &\iff a = -\frac{3}{5}.\end{aligned}$$

2. If f and g are both odd functions, so is $f + g$ because

$$(f + g)(-x) = f(-x) + g(-x) = -f(x) - g(x) = -(f(x) + g(x)) = -(f + g)(x).$$

Similarly, if f is an odd function and λ is a scalar, the function λf is also odd:

$$(\lambda f)(-x) = \lambda f(-x) = -\lambda f(x) = -(\lambda f)(x).$$

It follows that the set of odd functions is closed under addition and scalar multiplication. Hence it must be a subspace of $\mathcal{F}(-\infty, +\infty)$.

3. $\{\mathbf{u}_1, \mathbf{u}_2\}$ is a basis for \mathbb{R}^2 if and only if the two vectors \mathbf{u}_1 and \mathbf{u}_2 are linearly independent. This means that $\lambda_1\mathbf{u}_1 + \lambda_2\mathbf{u}_2 = \mathbf{0}$ happens only when $\lambda_1 = \lambda_2 = 0$. Now

$$\begin{aligned}\lambda_1\mathbf{u}_1 + \lambda_2\mathbf{u}_2 = \mathbf{0} &\iff \lambda_1(a\mathbf{v}_1 + b\mathbf{v}_2) + \lambda_2(c\mathbf{v}_1 + d\mathbf{v}_2) = \mathbf{0} \\ &\iff (a\lambda_1 + c\lambda_2)\mathbf{v}_1 + (b\lambda_1 + d\lambda_2)\mathbf{v}_2 = \mathbf{0} \\ &\iff a\lambda_1 + c\lambda_2 = b\lambda_1 + d\lambda_2 = 0 \quad (\text{since } \{\mathbf{v}_1, \mathbf{v}_2\} \text{ is a basis})\end{aligned}$$

It follows that \mathbf{u}_1 and \mathbf{u}_2 are linearly independent if and only if the homogeneous system

$$\begin{cases} a\lambda_1 + c\lambda_2 &= 0 \\ b\lambda_1 + d\lambda_2 &= 0 \end{cases}$$

has only the trivial solution $\lambda_1 = \lambda_2 = 0$. This happens precisely when the matrix

$$\begin{bmatrix} a & c \\ b & d \end{bmatrix}$$

is invertible, i.e., when $ad - bc \neq 0$.

4. We form the 4×4 matrix whose columns are the vectors $\mathbf{v}_1, \mathbf{v}_2, \mathbf{v}_3, \mathbf{v}_4$ and compute its determinant:

$$\begin{aligned} \det \begin{bmatrix} 1 & 1 & -2 & 2 \\ 1 & 0 & 1 & -2 \\ 2 & 0 & 3 & 0 \\ 0 & 0 & 1 & 5 \end{bmatrix} &= -\det \begin{bmatrix} 1 & 1 & -2 \\ 2 & 3 & 0 \\ 0 & 1 & 5 \end{bmatrix} \quad (\text{expansion along second column}) \\ &= -\left(\det \begin{bmatrix} 3 & 0 \\ 1 & 5 \end{bmatrix} - 2 \det \begin{bmatrix} 1 & -2 \\ 1 & 5 \end{bmatrix} \right) \quad (\text{expansion along first column}) \\ &= -(15 - 14) = -1 \end{aligned}$$

Since this determinant is non-zero, \mathcal{B} is a basis for \mathbb{R}^4 .

To find the coordinates of a generic vector $\mathbf{v} = (x, y, z, w)$ relative to \mathcal{B} , we have to express \mathbf{v} as a linear combination $a\mathbf{v}_1 + b\mathbf{v}_2 + c\mathbf{v}_3 + d\mathbf{v}_4$ and find the coefficients a, b, c, d in terms of x, y, z, w :

$$\begin{aligned} (x, y, z, w) &= a(1, 1, 2, 0) + b(1, 0, 0, 0) + c(-2, 1, 3, 1) + d(2, -2, 0, 5) \\ \Leftrightarrow \begin{cases} a + b - 2c + 2d &= x \\ a + c - 2d &= y \\ 2a + 3c &= z \\ c + 5d &= w \end{cases} \Leftrightarrow \begin{bmatrix} 1 & 1 & -2 & 2 \\ 1 & 0 & 1 & -2 \\ 2 & 0 & 3 & 0 \\ 0 & 0 & 1 & 5 \end{bmatrix} \begin{bmatrix} a \\ b \\ c \\ d \end{bmatrix} = \begin{bmatrix} x \\ y \\ z \\ w \end{bmatrix}. \end{aligned}$$

We solve this system by Gauss-Jordan elimination:

$$\begin{aligned} \begin{bmatrix} 1 & 1 & -2 & 2 & \vdots & x \\ 1 & 0 & 1 & -2 & \vdots & y \\ 2 & 0 & 3 & 0 & \vdots & z \\ 0 & 0 & 1 & 5 & \vdots & w \end{bmatrix} &\xrightarrow{-R_1+R_2, -2R_1+R_3} \begin{bmatrix} 1 & 1 & -2 & 2 & \vdots & x \\ 0 & -1 & 3 & -4 & \vdots & -x+y \\ 0 & -2 & 7 & -4 & \vdots & -2x+z \\ 0 & 0 & 1 & 5 & \vdots & w \end{bmatrix} \\ &\xrightarrow{-R_2, 2R_2+R_3} \begin{bmatrix} 1 & 1 & -2 & 2 & \vdots & x \\ 0 & 1 & -3 & 4 & \vdots & x-y \\ 0 & 0 & 1 & 4 & \vdots & -2y+z \\ 0 & 0 & 1 & 5 & \vdots & w \end{bmatrix} \xrightarrow{-R_3+R_4} \begin{bmatrix} 1 & 1 & -2 & 2 & \vdots & x \\ 0 & 1 & -3 & 4 & \vdots & x-y \\ 0 & 0 & 1 & 4 & \vdots & -2y+z \\ 0 & 0 & 0 & 1 & \vdots & 2y-z+w \end{bmatrix} \\ &\xrightarrow{-4R_4+R_3, -4R_4+R_2, -2R_4+R_1} \begin{bmatrix} 1 & 1 & -2 & 0 & \vdots & x-4y+2z-2w \\ 0 & 1 & -3 & 0 & \vdots & x-9y+4z-4w \\ 0 & 0 & 1 & 0 & \vdots & -10y+5z-4w \\ 0 & 0 & 0 & 1 & \vdots & 2y-z+w \end{bmatrix} \\ &\xrightarrow{3R_3+R_2, 2R_3+R_1} \begin{bmatrix} 1 & 1 & 0 & 0 & \vdots & x-24y+12z-10w \\ 0 & 1 & 0 & 0 & \vdots & x-39y+19z-16w \\ 0 & 0 & 1 & 0 & \vdots & -10y+5z-4w \\ 0 & 0 & 0 & 1 & \vdots & 2y-z+w \end{bmatrix} \xrightarrow{-R_2+R_1} \begin{bmatrix} 1 & 0 & 0 & 0 & \vdots & 15y-7z+6w \\ 0 & 1 & 0 & 0 & \vdots & x-39y+19z-16w \\ 0 & 0 & 1 & 0 & \vdots & -10y+5z-4w \\ 0 & 0 & 0 & 1 & \vdots & 2y-z+w \end{bmatrix} \end{aligned}$$

So the system has the solution

$$a = 15y - 7z + 6w, b = x - 39y + 19z - 16w, c = -10y + 5z - 4w, d = 2y - z + w.$$

Thus the coordinates of $\mathbf{v} = (x, y, z, w)$ relative to \mathcal{B} are

$$(x, y, z, w)_{\mathcal{B}} = (15y - 7z + 6w, x - 39y + 19z - 16w, -10y + 5z - 4w, 2y - z + w).$$

5. Let W be the set of all symmetric 3×3 matrices, i.e., all 3×3 matrices A such that $A^T = A$. Suppose A, B are in W and λ is any scalar. Then

$$(A + B)^T = A^T + B^T = A + B \quad \text{and} \quad (\lambda A)^T = \lambda A^T = \lambda A.$$

Thus both $A + B$ and λA are in W . This shows W is closed under addition and scalar multiplication, so it is a subspace of $\mathcal{M}_{3,3}$.

Now let us find a basis for W . Every matrix in W , being symmetric, has the form

$$\begin{bmatrix} a & b & c \\ b & d & e \\ c & e & f \end{bmatrix}$$

for some real numbers a, b, c, d, e, f . We can decompose this matrix as

$$\begin{bmatrix} a & b & c \\ b & d & e \\ c & e & f \end{bmatrix} = a \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} + b \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} + c \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix} + d \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} + e \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix} + f \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}.$$

If we set

$$\begin{aligned} A_1 &= \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} & A_2 &= \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix} & A_3 &= \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix} \\ A_4 &= \begin{bmatrix} 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} & A_5 &= \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix} & A_6 &= \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}, \end{aligned}$$

it follows that every matrix in W is a linear combination of $\{A_1, \dots, A_6\}$. In other words, $W = \text{span}\{A_1, \dots, A_6\}$. On the other hand, A_1, \dots, A_6 are linearly independent because if

$$aA_1 + bA_2 + cA_3 + dA_4 + eA_5 + fA_6 = 0$$

then

$$\begin{bmatrix} a & b & c \\ b & d & e \\ c & e & f \end{bmatrix} = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

which implies $a = b = c = d = e = f = 0$. Thus $\{A_1, \dots, A_6\}$ is a basis for W . In particular, $\dim(W) = 6$.

6. (i) $W = \{(a, b, c) : a + 2b - c = 0\}$. In other words, W consists of all vectors of the form $(a, b, a + 2b)$, where a, b are arbitrary real numbers. Since

$$(a, b, a + 2b) = a(1, 0, 1) + b(0, 1, 2),$$

it follows that every vector in W is a linear combination of $\mathbf{v}_1 = (1, 0, 1)$ and $\mathbf{v}_2 = (0, 1, 2)$. It is easy to see that $\mathbf{v}_1, \mathbf{v}_2$ are independent, so they must form a basis for W . In particular, $\dim(W) = 2$ (a plane through the origin).

(ii) $W = \{(a, b, c) : a = b = -c\}$. In other words, W consists of all vectors of the form $(a, a, -a)$, where a is an arbitrary real number. Since

$$(a, a, -a) = a(1, 1, -1),$$

it follows that every vector in W is a scalar multiple of $\mathbf{v}_1 = (1, 1, -1)$ so \mathbf{v}_1 alone must form a basis for W . In particular, $\dim(W) = 1$ (a line through the origin).

7. (i) Augment the vector $\mathbf{b} = \begin{bmatrix} a \\ b \\ c \\ d \end{bmatrix}$ to A and reduce to row-echelon form:

$$\begin{bmatrix} 1 & 3 & 1 & -2 & -3 & \vdots & a \\ 1 & 4 & 3 & -1 & -4 & \vdots & b \\ 2 & 3 & -4 & -7 & -3 & \vdots & c \\ 3 & 8 & 1 & -7 & -8 & \vdots & d \end{bmatrix} \xrightarrow{-R_1+R_2, -2R_1+R_3, -3R_1+R_4} \begin{bmatrix} 1 & 3 & 1 & -2 & -3 & \vdots & a \\ 0 & 1 & 2 & 1 & -1 & \vdots & -a+b \\ 0 & -3 & -6 & -3 & 3 & \vdots & -2a+c \\ 0 & -1 & -2 & -1 & 1 & \vdots & -3a+d \end{bmatrix}$$

$$\xrightarrow{3R_2+R_3, R_2+R_4} \begin{bmatrix} 1 & 3 & 1 & -2 & -3 & \vdots & a \\ 0 & 1 & 2 & 1 & -1 & \vdots & -a+b \\ 0 & 0 & 0 & 0 & 0 & \vdots & -5a+3b+c \\ 0 & 0 & 0 & 0 & 0 & \vdots & -4a+b+d \end{bmatrix}$$

It follows that

$$\mathbf{Ax} = \mathbf{b} = \begin{bmatrix} a \\ b \\ c \\ d \end{bmatrix} \text{ is consistent } \iff -5a + 3b + c = -4a + b + d = 0.$$

(ii) We already have the row-echelon form R of A :

$$R = \begin{bmatrix} 1 & 3 & 1 & -2 & -3 \\ 0 & 1 & 2 & 1 & -1 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

A basis for $\text{Row}(A)$ will consist of the non-zero rows of R :

$$\begin{bmatrix} 1 & 3 & 1 & -2 & -3 \end{bmatrix} \quad \begin{bmatrix} 0 & 1 & 2 & 1 & -1 \end{bmatrix}.$$

Since the leading 1's in R occur along the first and second columns, a basis for $\text{Col}(A)$ will consist of the first and second columns of A :

$$\begin{bmatrix} 1 \\ 1 \\ 2 \\ 3 \end{bmatrix} \quad \begin{bmatrix} 3 \\ 4 \\ 3 \\ 8 \end{bmatrix}.$$

Finally, to find a basis for $\text{Null}(A)$, let us solve the system $A\mathbf{x} = 0$, or equivalently, $R\mathbf{x} = 0$:

$$\begin{cases} x_1 + 3x_2 + x_3 - 2x_4 - 3x_5 = 0 \\ x_2 + 2x_3 + x_4 - x_5 = 0 \end{cases}$$

The leading variables are x_1, x_2 and the free variables are x_3, x_4, x_5 . So the solutions of the system are obtained by assigning arbitrary values to x_3, x_4, x_5 and solving for x_1, x_2 :

$$\begin{cases} x_1 = 5r + 5s \\ x_2 = -2r - s + t \\ x_3 = r \\ x_4 = s \\ x_5 = t \end{cases} \quad (r, s, t \text{ are arbitrary})$$

Thus

$$\mathbf{x} \text{ is in } \text{Null}(A) \iff \mathbf{x} = \begin{bmatrix} 5r + 5s \\ -2r - s + t \\ r \\ s \\ t \end{bmatrix} = r \begin{bmatrix} 5 \\ -2 \\ 1 \\ 0 \\ 0 \end{bmatrix} + s \begin{bmatrix} 5 \\ -1 \\ 0 \\ 1 \\ 0 \end{bmatrix} + t \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \\ 1 \end{bmatrix}.$$

It follows that a basis for $\text{Null}(A)$ is given by the vectors

$$\begin{bmatrix} 5 \\ -2 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 5 \\ -1 \\ 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 0 \\ 0 \\ 1 \end{bmatrix}.$$

(iii) $\text{rank}(A) = \dim \text{Row}(A) = \dim \text{Col}(A) = 2$ and $\text{nullity}(A) = \dim \text{Null}(A) = 3$, so $\text{rank}(A) + \text{nullity}(A) = 5$.