### Motion in space

If  $\vec{\mathbf{r}}(t)$  is the vector position of a particle, then

- $\vec{\mathbf{r}}'(t) = \vec{\mathbf{v}}(t)$  is the vector velocity of the particle.
- $|\vec{\mathbf{r}}'(t)| = |\vec{\mathbf{v}}(t)| = \text{speed of the particle.}$
- $\vec{r}''(t) = \vec{a}(t)$  is the vector acceleration of the particle.

We can use  $\vec{a}(t)$  to find the force that an object exerts:  $\vec{F}(t) = m \vec{a}(t)$ 

Example. Suppose that a mass of 40 kg starts with init. pos'n  $\langle 1, 0, 0 \rangle$ , initial velocity  $\langle 1, -1, 1 \rangle$  and has acceleration  $\vec{a}(t) = \langle 4t, 6t, 1 \rangle$ .

- (a) Find the position and velocity of the particle as a function of t.
- (b) Determine the force that the particle exerts at time t=2.

Example. Show that if a particle moves with constant speed, then the velocity and acceleration vectors are orthogonal.

# Arc length

The arc length of a vector function is calculated by:

$$\int_{t=a}^{t=b} \sqrt{f'(t)^2 + g'(t)^2 + h'(t)^2} dt = \int_{t=a}^{t=b} |\vec{\mathbf{r}}'(t)| dt$$

The arc length function is  $s(t) = \int_{u=a}^{u=\tau} |\vec{\mathbf{r}}'(u)| du$ .

- $\blacktriangleright$  We are using u as the parametrization variable instead of t.
- ► This is a function of t, telling how far along the curve you have traveled since a.

Example. Determine the distance that a particle travels from its initial position (1,0,0) to any point on the curve

$$\vec{\mathbf{r}}(t) = \cos t \, \vec{\mathbf{i}} + \sin t \, \vec{\mathbf{j}} + t \, \vec{\mathbf{k}}.$$

Answer: We are looking for s(t) starting at t =\_\_\_\_.

$$s(t) = \int_{u=0}^{u=t} \sqrt{\frac{1}{u-1}} du = 0$$

The distance travelled from time 0 to time t is s(t) =\_\_\_\_\_.

# Reparametrization with respect to arc length

You may want to reparametrize your curve so that

one unit in your parameter  $\longleftrightarrow$  one unit in distance

To do this, we need to replace t by s.

Since we have s as a function of t, we need the inverse function!

In our example,  $s = \sqrt{2}t$ , so  $t = \frac{s}{\sqrt{2}}$ . Substituting,

$$\vec{\mathbf{r}}(s) = \cos \frac{s}{\sqrt{2}} \vec{\mathbf{i}} + \sin \frac{s}{\sqrt{2}} \vec{\mathbf{j}} + \frac{s}{\sqrt{2}} \vec{\mathbf{k}}.$$

### Frenet Frame

There are many different parametrizations of any one curve.

The vectors  $\vec{\mathbf{r}}(t)$ ,  $\vec{\mathbf{v}}(t)$ ,  $\vec{\mathbf{a}}(t)$  depend on the parameter.

But the curve itself has intrinsic properties. At every point:

Three natural vectors make up the Frenet frame, or TNB frame.

- $\vec{\mathsf{T}}$  The direction of the tangent vector.  $\vec{\mathsf{T}}(t) = \frac{\vec{\mathsf{r}}'(t)}{|\vec{\mathsf{r}}'(t)|}$ .
- $\vec{N}$  The direction in which the curve is turning.  $\vec{N}(t) = \frac{\vec{T}'(t)}{|\vec{T}'(t)|}$ .
- $\vec{\mathbf{B}}$  The third vector that completes  $\perp$  basis.  $\vec{\mathbf{B}}(t) = \vec{\mathbf{T}}(t) \times \vec{\mathbf{N}}(t)$

A number that tells how bendy or twisty the curve is.

**Definition:** The **curvature**  $\kappa(t)$  of a curve ("kappa") tells how quickly  $\vec{\mathbf{T}}$  is changing with respect to distance traveled.

$$\kappa = \left| \frac{d\vec{\mathbf{T}}}{ds} \right| \stackrel{\text{chain rule}}{=} \left| \frac{\frac{d\vec{\mathbf{T}}}{dt}}{\frac{ds}{dt}} \right| = \frac{|\vec{\mathbf{T}}'(t)|}{|\vec{\mathbf{r}}'(t)|} \stackrel{\text{algebra}}{=} \frac{|\vec{\mathbf{r}}'(t) \times \vec{\mathbf{r}}''(t)|}{|\vec{\mathbf{r}}'(t)|^3}.$$

The circle that lies along the curve has radius  $1/\kappa$ . (!)

#### Curvature

Example. Determine the vectors of the Frenet frame and the curvature of the curve  $\vec{\mathbf{r}}(t) = \langle \cos t, \sin t, t \rangle$ .

Frenet frame: We need  $\vec{\mathbf{r}}'(t) = \langle -\sin t, \cos t, 1 \rangle$  and  $|\vec{\mathbf{r}}'(t)| = \underline{\hspace{1cm}}$ 

Then 
$$\vec{\mathbf{T}}(t) = \frac{\vec{\mathbf{r}}'(t)}{|\vec{\mathbf{r}}'(t)|} = \langle \frac{-\sin t}{\sqrt{2}}, \frac{\cos t}{\sqrt{2}}, \frac{1}{\sqrt{2}} \rangle$$
,

From this we find that  $\vec{\mathbf{T}}'(t) = \langle \frac{-\cos t}{\sqrt{2}}, \frac{-\sin t}{\sqrt{2}}, 0 \rangle$ , so  $|\vec{\mathbf{T}}'(t)| = \underline{\qquad}$ .

Then 
$$\vec{\mathbf{N}}(t) = \frac{\vec{\mathbf{T}}'(t)}{|\vec{\mathbf{T}}'(t)|} = \langle -\cos t, -\sin t, 0 \rangle$$
.

Now 
$$\vec{\mathbf{B}}(t) = \vec{\mathbf{T}}(t) \times \vec{\mathbf{N}}(t) = \frac{1}{\sqrt{2}} \begin{vmatrix} \vec{\mathbf{i}} & \vec{\mathbf{j}} & \vec{\mathbf{k}} \\ -\sin t & \cos t & 1 \\ -\cos t & -\sin t & 0 \end{vmatrix} =$$

The curvature 
$$\kappa(t) = \frac{|\vec{\mathbf{T}}'(t)|}{|\vec{\mathbf{r}}'(t)|} =$$

Question: Should  $\kappa(t)$  be a constant?

# Components of Acceleration

The curvature tells us about the centripetal force we feel.

**Key idea:** Understand  $\vec{a}$  in terms of the Frenet frame:

How much of the acceleration is toward  $\vec{T}$ ,  $\vec{N}$ , and  $\vec{B}$ ?

Differentiate  $\vec{\mathbf{v}}(t) = v(t)\vec{\mathbf{T}}(t)$ . (magnitude (speed) times unit direction)

$$\vec{\mathbf{a}} = \mathbf{v}'\vec{\mathbf{T}} + \mathbf{v}\vec{\mathbf{T}}' = \mathbf{v}'\vec{\mathbf{T}} + \mathbf{v}(|\vec{\mathbf{T}}'|\vec{\mathbf{N}}) = \mathbf{v}'\vec{\mathbf{T}} + \kappa \mathbf{v}^2\vec{\mathbf{N}}.$$

ightharpoonup All acceleration is toward  $\vec{T}$  and  $\vec{N}$ . (Not to  $\vec{B}$ .)

 $a_T$  Toward  $\vec{\mathbf{T}}$ :  $a_T = v'$  is rate of change of speed.

 $a_N$  Toward  $\vec{\mathbf{N}}$ :  $a_N = \kappa v^2$ . Curvature times speed squared!

Solve for  $a_T$ ,  $a_N$  in terms of  $\vec{\mathbf{r}}(t)$ .

First, 
$$\vec{\mathbf{v}} \cdot \vec{\mathbf{a}} = v \vec{\mathbf{T}} \cdot (v' \vec{\mathbf{T}} + \kappa v^2 \vec{\mathbf{N}}) = vv' \vec{\mathbf{T}} \cdot \vec{\mathbf{T}} + \kappa v^3 \vec{\mathbf{T}} \cdot \vec{\mathbf{N}} = vv'$$

So 
$$a_T = v' = \frac{\vec{\mathbf{v}} \cdot \vec{\mathbf{a}}}{v} = \frac{\vec{\mathbf{r}}'(t) \cdot \vec{\mathbf{r}}''(t)}{|\vec{\mathbf{r}}'(t)|}$$
 and  $a_N = \kappa v^2 = \frac{|\vec{\mathbf{r}}'(t) \times \vec{\mathbf{r}}''(t)|}{|\vec{\mathbf{r}}'(t)|}$  Symmetry!

Example. Find tang'l, normal comp's of acceleration for  $\vec{\mathbf{r}} = \langle t, 2t, t^2 \rangle$ .