## Motion in space

If $\overrightarrow{\mathbf{r}}(t)$ is the vector position of a particle, then

- $\overrightarrow{\mathbf{r}}^{\prime}(t)=\overrightarrow{\mathbf{v}}(t)$ is the vector velocity of the particle.
- $\left|\overrightarrow{\mathbf{r}}^{\prime}(t)\right|=|\overrightarrow{\mathbf{v}}(t)|=$ speed of the particle.
- $\overrightarrow{\mathbf{r}}^{\prime \prime}(t)=\overrightarrow{\mathbf{a}}(t)$ is the vector acceleration of the particle.

We can use $\overrightarrow{\mathbf{a}}(t)$ to find the force that an object exerts: $\overrightarrow{\mathbf{F}}(t)=m \overrightarrow{\mathbf{a}}(t)$
Example. Suppose that a mass of 40 kg starts with init. pos'n $\langle 1,0,0\rangle$, initial velocity $\langle 1,-1,1\rangle$ and has acceleration $\overrightarrow{\mathbf{a}}(t)=\langle 4 t, 6 t, 1\rangle$.
(a) Find the position and velocity of the particle as a function of $t$.
(b) Determine the force that the particle exerts at time $t=2$.

Example. Show that if a particle moves with constant speed, then the velocity and acceleration vectors are orthogonal.

## Arc length

The arc length of a vector function is calculated by:

$$
\int_{t=a}^{t=b} \sqrt{f^{\prime}(t)^{2}+g^{\prime}(t)^{2}+h^{\prime}(t)^{2}} d t=\int_{t=a}^{t=b}\left|\overrightarrow{\mathbf{r}}^{\prime}(t)\right| d t
$$

The arc length function is $s(t)=\int_{u=a}^{u=t}\left|\overrightarrow{\mathbf{r}}^{\prime}(u)\right| d u$.

- We are using $u$ as the parametrization variable instead of $t$.
- This is a function of $t$, telling how far along the curve you have traveled since $a$.
Example. Determine the distance that a particle travels from its initial position $(1,0,0)$ to any point on the curve

$$
\overrightarrow{\mathbf{r}}(t)=\cos t \overrightarrow{\mathbf{i}}+\sin t \overrightarrow{\mathbf{j}}+t \overrightarrow{\mathbf{k}} .
$$

Answer: We are looking for $s(t)$ starting at $t=$ $\qquad$ .
$s(t)=\int_{u=0}^{u=t} \sqrt{\square} d u=$
The distance travelled from time 0 to time $t$ is $s(t)=$ $\qquad$ .

## Reparametrization with respect to arc length

You may want to reparametrize your curve so that one unit in your parameter $\longleftrightarrow$ one unit in distance

To do this, we need to replace $t$ by $s$.
Since we have $s$ as a function of $t$, we need the inverse function!
In our example, $s=\sqrt{2} t$, so $t=\frac{s}{\sqrt{2}}$. Substituting,

$$
\overrightarrow{\mathbf{r}}(s)=\cos \frac{s}{\sqrt{2}} \overrightarrow{\mathbf{i}}+\sin \frac{s}{\sqrt{2}} \overrightarrow{\mathbf{j}}+\frac{s}{\sqrt{2}} \overrightarrow{\mathbf{k}} .
$$

## Frenet Frame

There are many different parametrizations of any one curve.
The vectors $\overrightarrow{\mathbf{r}}(t), \overrightarrow{\mathbf{v}}(t), \overrightarrow{\mathbf{a}}(t)$ depend on the parameter.
But the curve itself has intrinsic properties. At every point:
Three natural vectors make up the Frenet frame, or TNB frame.
$\vec{\top}$ The direction of the tangent vector. $\overrightarrow{\mathrm{T}}(t)=\frac{\overrightarrow{\mathbf{r}}^{\prime}(t)}{\left|\overrightarrow{\mathbf{r}}^{\prime}(t)\right|}$.
$\overrightarrow{\mathbf{N}}$ The direction in which the curve is turning. $\overrightarrow{\mathbf{N}}(t)=\frac{\overrightarrow{\mathbf{T}}^{\prime}(t)}{\left|\overrightarrow{\mathbf{T}}^{\prime}(t)\right|}$.
$\overrightarrow{\mathbf{B}}$ The third vector that completes $\perp$ basis. $\overrightarrow{\mathbf{B}}(t)=\overrightarrow{\mathbf{T}}(t) \times \overrightarrow{\mathbf{N}}(t)$
A number that tells how bendy or twisty the curve is.
Definition: The curvature $\kappa(t)$ of a curve ("kappa") tells how quickly $\overrightarrow{\mathbf{T}}$ is changing with respect to distance traveled.

$$
\kappa=\left|\frac{d \overrightarrow{\mathbf{T}}}{d s}\right| \stackrel{\text { chain rule }}{=}\left|\frac{\frac{d \overrightarrow{\mathbf{T}}}{d t}}{\frac{d s}{d t}}\right|=\frac{\left|\overrightarrow{\mathbf{T}}^{\prime}(t)\right|}{\left|\overrightarrow{\mathbf{r}}^{\prime}(t)\right|} \stackrel{\text { algebra }}{=} \frac{\left|\overrightarrow{\mathbf{r}}^{\prime}(t) \times \overrightarrow{\mathbf{r}}^{\prime \prime}(t)\right|}{\left|\overrightarrow{\mathbf{r}}^{\prime}(t)\right|^{3}} .
$$

The circle that lies along the curve has radius $1 / \kappa$. (!)

## Curvature

Example. Determine the vectors of the Frenet frame and the curvature of the curve $\overrightarrow{\mathbf{r}}(t)=\langle\cos t, \sin t, t\rangle$.
Frenet frame: We need $\overrightarrow{\mathbf{r}}^{\prime}(t)=\langle-\sin t, \cos t, 1\rangle$ and $\left|\overrightarrow{\mathbf{r}}^{\prime}(t)\right|=$ $\qquad$ .
Then $\overrightarrow{\mathbf{T}}(t)=\frac{\vec{r}^{\prime}(t)}{\left|\vec{r}^{\prime}(t)\right|}=\left\langle\frac{-\sin t}{\sqrt{2}}, \frac{\cos t}{\sqrt{2}}, \frac{1}{\sqrt{2}}\right\rangle$,
From this we find that $\overrightarrow{\mathbf{T}}^{\prime}(t)=\left\langle\frac{-\cos t}{\sqrt{2}}, \frac{-\sin t}{\sqrt{2}}, 0\right\rangle$, so $\left|\overrightarrow{\mathbf{T}}^{\prime}(t)\right|=$ $\qquad$ .
Then $\overrightarrow{\mathbf{N}}(t)=\frac{\overrightarrow{\mathbf{T}}^{\prime}(t)}{\left|\overrightarrow{\mathbf{T}^{\prime}}(t)\right|}=\langle-\cos t,-\sin t, 0\rangle$.
Now $\overrightarrow{\mathbf{B}}(t)=\overrightarrow{\mathbf{T}}(t) \times \overrightarrow{\mathbf{N}}(t)=\frac{1}{\sqrt{2}}\left|\begin{array}{ccc}\overrightarrow{\mathbf{i}} & \overrightarrow{\mathbf{j}} & \overrightarrow{\mathbf{k}} \\ -\sin t & \cos t & 1 \\ -\cos t & -\sin t & 0\end{array}\right|=$
The curvature $\kappa(t)=\frac{\left|\overrightarrow{\mathbf{T}}^{\prime}(t)\right|}{\left|\overrightarrow{\mathbf{r}}^{\prime}(t)\right|}=$
Question: Should $\kappa(t)$ be a constant?

## Components of Acceleration

The curvature tells us about the centripetal force we feel.
Key idea: Understand $\overrightarrow{\mathbf{a}}$ in terms of the Frenet frame:
How much of the acceleration is toward $\overrightarrow{\mathbf{T}}, \overrightarrow{\mathbf{N}}$, and $\overrightarrow{\mathbf{B}}$ ?
Differentiate $\overrightarrow{\mathbf{v}}(t)=v(t) \overrightarrow{\mathbf{T}}(t)$. (magnitude (speed) times unit direction)

$$
\overrightarrow{\mathbf{a}}=v^{\prime} \overrightarrow{\mathbf{T}}+v \overrightarrow{\mathbf{T}}^{\prime}=v^{\prime} \overrightarrow{\mathbf{T}}+v\left(\left|\overrightarrow{\mathbf{T}^{\prime}}\right| \overrightarrow{\mathbf{N}}\right)=v^{\prime} \overrightarrow{\mathbf{T}}+\kappa v^{2} \overrightarrow{\mathbf{N}} .
$$

- All acceleration is toward $\overrightarrow{\mathbf{T}}$ and $\overrightarrow{\mathbf{N}}$. (Not to $\overrightarrow{\mathbf{B}}$.)
$a_{T}$ Toward $\overrightarrow{\mathbf{T}}: a_{T}=v^{\prime}$ is rate of change of speed.
$a_{N}$ Toward $\overrightarrow{\mathbf{N}}: a_{N}=\kappa v^{2}$. Curvature times speed squared!
Solve for $a_{T}, a_{N}$ in terms of $\overrightarrow{\boldsymbol{r}}(t)$.
First, $\overrightarrow{\mathbf{v}} \cdot \overrightarrow{\mathbf{a}}=v \overrightarrow{\mathbf{T}} \cdot\left(v^{\prime} \overrightarrow{\mathbf{T}}+\kappa v^{2} \overrightarrow{\mathbf{N}}\right)=v v^{\prime} \overrightarrow{\mathbf{T}} \cdot \overrightarrow{\mathbf{T}}+\kappa v^{3} \overrightarrow{\mathbf{T}} \cdot \overrightarrow{\mathbf{N}}=v v^{\prime}$

$$
\text { So } a_{T}=v^{\prime}=\frac{\vec{v} \cdot \overrightarrow{\mathbf{a}}}{v}=\frac{\vec{r}^{\prime}(t) \cdot \vec{r}^{\prime \prime}(t)}{\left|\vec{r}^{\prime}(t)\right|} \text { and } a_{N}=\kappa v^{2}=\frac{\left|\overrightarrow{r^{\prime}}(t) \times \vec{r}^{\prime \prime}(t)\right|}{\left|\vec{r}^{\prime}(t)\right|} \begin{gathered}
\text { Nice } \\
\text { symmetry! }
\end{gathered}
$$

Example. Find tang'l, normal comp's of acceleration for $\overrightarrow{\mathbf{r}}=\left\langle t, 2 t, t^{2}\right\rangle$.

