APPLICATIONS OF THE \mathcal{L}_2 -TRANSFORM TO PDE'S

The goal of this article is to illustrate the applicability of the \mathcal{L}_2 -transform to solving certain partial differential equations. Recall that a function $f : [0, \infty) \to \mathbb{R}$ is called *exponential squared order* if $\lim_{x \to \infty} f(x)e^{-x^2} = 0$.

Definition 1. For any exponential squared order function $f(t)$, the \mathcal{L}_2 transform of f is defined as:

$$
\mathcal{L}_2\{f(x);s\} = \int_0^\infty x e^{-x^2 s^2} f(x) dx
$$

Here is a useful example. For $n \geq 0$ we have:

(1)
$$
\mathcal{L}_2\{x^{2n};s\} = \frac{n!}{2s^{2n+2}}
$$

In the case $n = 0$, we obtain

$$
\mathcal{L}_2\{1;s\} = \int_0^\infty x e^{-x^2 s^2} dx = \frac{1}{2s^2}
$$

and for $n = 1$, through integration by parts, we have

$$
\mathcal{L}_2\{x^{2n};s\} = \left(\frac{-x^2}{2s^2}e^{-x^2s^2}\right)\Big|_0^\infty + \frac{1}{s^2}\int_0^\infty e^{-x^2s^2}xdx = \frac{1}{s^2}\left(\frac{1}{2s^2}\right)
$$

Property (1) then follows by a simple induction.

There is a differential operator δ_x , defined by

$$
\delta_x = \frac{1}{x} \cdot \frac{d}{dx}
$$

which has some nice properties with respect to the \mathcal{L}_2 -transform, which we now recall. See also

Proposition 1. Let f be a function of exponential squared order. Then

(2)
$$
\mathcal{L}_2\{\delta_x f(x); s\} = 2s^2 \mathcal{L}_2\{f(x); s\} - f(0^+)
$$

and for all $n \geq 0$

(3)
$$
\mathcal{L}_2\{x^{2n}f(x);s\} = \frac{(-1)^n}{2^n} \delta_s^n \mathcal{L}_2\{f(x);s\}
$$

Proof. For the first claim, we calculate

$$
\int_0^{\infty} x e^{-x^2 s^2} \delta_x f(x) dx = \int_0^{\infty} x e^{-x^2 s^2} \cdot \frac{1}{x} \frac{d}{dx} f(x) (dx) = \int_0^{\infty} e^{-x^2 s^2} f'(x) dx
$$

and, integrating by parts, we get:

$$
= f(x)(e^{-x^2s^2})\Big|_0^\infty + \int_0^\infty 2xs^2xe^{-x^2s^2}f(x)dx
$$

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Evaluating from 0 to ∞ , using the fact that f is exponential squared order, we can write this expression in terms of the \mathcal{L}_2 transform:

$$
2s^2\mathcal{L}_2\{f(x);s\} - f(0^+).
$$

For property (3) , taking the case in which n=1, we get:

$$
\delta_s \mathcal{L}_2 \{ f(x); s \} = \delta_s \int_0^\infty x e^{-x^2 s^2} f(x) dx
$$

We can take the differential operator δ_s into the integral, yielding:

$$
\int_0^\infty \frac{1}{s} \frac{d}{ds} \cdot xe^{-x^2 s^2} f(x) dx \Rightarrow \int_0^\infty \frac{1}{s} \cdot -2x^2 s \cdot xe^{-x^2 s^2} f(x) dx = -2 \int_0^\infty x^2 \cdot xe^{-x^2 s^2} f(x) dx
$$

We can notice here that the last term of this equation is really equal to:

$$
\mathcal{L}_2\{-2x^2f(x);s\}
$$

Which is an alternative representation of property (3). Applying the application of the differential operator with respect to s to this result, we get:

$$
\delta_s \mathcal{L}_2 \{-2x^2 f(x); s\} = \delta_s - 2 \int_0^\infty x^2 x e^{-x^2 s^2} f(x) dx
$$

As we did before, we re-write the differential operator and apply it within the integeral:

$$
-2\int_0^\infty \frac{1}{s} \frac{d}{ds} \cdot x^2 x e^{-x^2 s^2} f(x) dx = -2\int_0^\infty \frac{1}{s} x^2 x^2 x e^{-x^2 s^2} f(x) -2x^2 s dx = 4\int_0^\infty x^2 \cdot x^2 x e^{-x^2 s^2} f(x) dx
$$

Which we can see is realy equal to :

$$
4\mathcal{L}_2\{x^4f(x);s\}
$$

As we can see through induction, for a general $n \geq 1$, we have:

$$
\delta_s^n \mathcal{L}_2\{f(x);s\} = -2^n \mathcal{L}_2\{x^{2n}f(x);s\}
$$

Or, written alternatively,

$$
\mathcal{L}_2\{x^{2n}f(x);s\} = \frac{(-1)^n}{2^n} \delta_s^n \mathcal{L}_2\{f(x);s\}
$$

1. The \mathcal{L}_2 Convolution

A binary operation (\star) called the convolution of two functions f, g is defined as follows:

$$
(f \star g)(t) = \int_0^t x f(\sqrt{t^2 - x^2}) g(x) dx
$$

It can be shown that this operation is associative and commutative. Most importantly for our purposes, the following are true:

$$
\mathcal{L}_2\{f \star g; s\} = \mathcal{L}_2(f) \cdot \mathcal{L}_2(g)
$$

and:

(4)
$$
\mathcal{L}_2\{f_1 \star f_2 \star \ldots \star f_n; s\} = \mathcal{L}_2(f_1) \cdot \mathcal{L}_2(f_2) \cdot \ldots \cdot \mathcal{L}_2(f_n)
$$

From which it follows:

(5)
$$
\mathcal{L}^{-1} \{\hat{f}_1 \cdot \hat{f}_2 \cdot ... \cdot \hat{f}_n\} = f_1 \star f_2 \star ... \star f_n
$$

2. Applications

Consider the following partial differential equation :

(6)
$$
t^3 u_{tx} + 2xu = 0 \text{ and } u(0^+, t) = 0
$$

where $u = u(x, t)$ for $x, t > 0$ and $u(0^+, t) = \lim_{x \to 0^+} u(x, t)$.

Writing the PDE in Equation 6 in terms of the differential operator, we have:

$$
t^3 \frac{1}{x} \frac{d}{dx} u_t + 2u = 0
$$

or equivalently,

$$
t^3 \delta_x u_t = -2u.
$$

Taking the \mathcal{L}_2 transform of both sides and using property (3) we obtain

$$
2s^2t^3\hat{u}_t - u(0^+,t) = -2\hat{u}
$$

where $\hat{u} = \hat{u}(s, t) = \mathcal{L}_2\{u(x, t); s\}$. Equivalently,

$$
\hat{u}_t = \frac{-1}{s^2 t^3} \hat{u} + \frac{u(0^+, t)}{2s^2 t^3}.
$$

By the initial condition in (6), this last term is zero. One solution to this differential equation is

$$
\hat{u}(s,t) = \frac{1}{2s^2} e^{\frac{t^{-2}s^{-2}}{2}}
$$

We now write $\hat{u}(s,t)$ as a series to obtain:

$$
\hat{u}(s,t) = \frac{1}{2s^2} \sum_{n=0}^{\infty} \frac{\left(\frac{s^2 t^2}{2}\right)^{-2n}}{n!} = \sum_{n=0}^{\infty} \frac{2^n}{2s^{2n+2} t^{2n} n!}.
$$

Using property (1), we can calculate that $u(x,t) = \mathcal{L}_2^{-1}\{(u(s,t);x\}$ is

$$
u(x,t) = \sum_{n=0}^{\infty} \frac{2^n x^{2n}}{t^{2n} (n!)^2}.
$$

3. Further Generalizations

Similarly, we can solve all partial differential equations of the form:

$$
0 = f(t)u + f(t)\frac{1}{x}u_x + g(t)\frac{1}{x}u_{xt}
$$

Taking the \mathcal{L}_2 transform, we compute:

$$
0 = f(t)\hat{u} + f(t)2s^2\hat{u} + g(t)2s^2\hat{u}_t
$$

Rearranging:

$$
\frac{\hat{u}_t}{\hat{u}} = -\frac{(1+2s^2)}{2s^2} \cdot M(t)
$$

Where $M(t) = \frac{f(t)}{g(t)}$. Claiming that L(s) is any function of s, a solution for \hat{u} is as follows:

$$
\hat{u}(s,t) = e^{\frac{-(1+2s^2)}{2s^2} \cdot \int_0^t M(w)dw} \cdot L(s) = e^{\int_0^t M(w)dw} \cdot e^{\frac{-\int_0^t M(w)dw}{2s^2} \cdot L(s)}
$$

Writing this as a series, denoting $\int_0^t M(w)dw$ as \mathcal{M} , and letting $L(s) = \frac{1}{-s^2}$, we get:

$$
\hat{u} = \frac{1}{-s^2} \sum_{n=0}^{\infty} \frac{-\mathcal{M}^n}{n! \cdot (2s^2)^n} \cdot \sum_{n=0}^{\infty} \frac{\mathcal{M}^n}{n!} = \sum_{n=0}^{\infty} \frac{\mathcal{M}^n}{n! \cdot (2^n s^{n+2})} \cdot \sum_{n=0}^{\infty} \frac{\mathcal{M}^n}{n!}
$$

$$
= \sum_{n=0}^{\infty} \frac{\mathcal{M}^n}{n! \cdot 2^{(n-1)} \cdot (2s^{n+2})} \cdot \sum_{n=0}^{\infty} \frac{\mathcal{M}^n}{n!}
$$

using identity (2), and taking the \mathcal{L}_2 inverse transform, we claim that:

$$
u(x,t) = \sum_{n=0}^{\infty} \frac{\mathcal{M}^n \cdot x^{2n}}{(n!)^2 \cdot 2^{n-1}} \cdot \sum_{n=0}^{\infty} \frac{\mathcal{M}^n}{2n!}
$$

Lastly, we can always solve the following types of partial differential equations:

$$
0 = f(t)u + f(t)\frac{1}{x}u_x + g(t)u_t + g(t)u + xt
$$

Taking the \mathcal{L}_2 transform, we get:

$$
0 = \hat{u}(1 + 2s^s) f(t) + \hat{u}_t (1 + 2s^2) g(t) \Rightarrow \frac{\hat{u}_t}{\hat{u}} = J(t)
$$

Where $J(t) = -\frac{g(t)}{f(t)}$ $\frac{g(t)}{f(t)}$. This implies that a solution for \hat{u} is as follows:

$$
\hat{u}(s,t) = e^{\int_0^t J(w)dw} \cdot L(s)
$$

Where $L(s)$ is an arbitrary function of s. Representing this expression as a series, and letting $L(s) = \frac{1}{2s^2}$, we get:

$$
\hat{u} = \sum_{n=0}^{\infty} \frac{(\int_0^t J(w)dw)^n}{n! \cdot 2y^2}
$$

And after applying the \mathcal{L}_2 inverse, we get the following solution for $u(x,t)$:

$$
u(x,t) = x^0 \cdot e^{\int_0^t J(w)dw}
$$

4. An Application to a Partial Differential Equation of Exponential Squared Order

Consider the following partial differential equation, with the following condition:

$$
0 = g(t)u - f(t)u_t + \frac{1}{x}f(x)u_{xt} \qquad u(0^+, t) = 0
$$

Writing this equation in terms of the differential operator,

$$
0 = g(t)u - f(t)u_t + \delta_x f(t)u_t
$$

and taking the \mathcal{L}_2 transform of it, we get:

$$
0 = g(t)\hat{u}_t - f(t)\hat{u}_t + 2s^2 f(t)\hat{u}_t
$$

Rearranging, we get:

$$
0 = g(t)u + f(t)\hat{f}_t(-1 + 2s^2)
$$

Which leads to:

$$
\frac{\hat{u}_t}{\hat{u}} = -\frac{1}{-1 + 2s^2} \cdot H(t)
$$

Where $H(t) = \frac{g(t)}{h(t)}$. This implies that a solution for \hat{u} is as follows:

$$
\hat{u}(s,t) = e^{\frac{-1}{-1+2s^2} \cdot \int_0^t H(w)dw}
$$

Writing this solution as a series, we get:

$$
\hat{u}(s,t) = \sum_{n=0}^{\infty} \frac{\left(\int_0^t H(w)dw\right)^n}{n!} \cdot \left(\frac{1}{-1+2s^2}\right)^n
$$

from (4), (5) and the following identity:

$$
\mathcal{L}_2\{e^{ax^2};s\} = \frac{1}{-2a+2s^2}
$$

We can arrive at the following solution:

$$
\mathcal{L}_2^{-1}\{\hat{u}(s,t)\} = \sum_{n=1}^{\infty} \left(\frac{(\int_0^t H(w)dw)^n}{n!} \cdot (e^{(1/2)x^2})^{\star_n} \right)
$$

Where $e^{(1/2)e^2}$ ^{*n} represents the following:

$$
\underbrace{e^{(1/2)e^2} \star e^{(1/2)e^2} \cdots \star e^{(1/2)e^2}}_{n}
$$

Which leads the following proposition, which can be shown through induction:

$$
(e^{(1/2)e^2})^{\star_n} = \frac{1}{2^{n-1}} \cdot \frac{x^{2(n-1)} \cdot e^{(1/2)x^2}}{(n-1)!}
$$

After a substitution, we have the following solution for $u(x, t)$:

$$
u(x,t) = \sum_{n=1}^{\infty} \left(\frac{\left(\int_0^t H(w)dw\right)^n}{n!} \cdot \frac{1}{2^{n-1}} \cdot \frac{x^{2(n-1)} \cdot e^{(1/2)x^2}}{(n-1)!} \right)
$$

Notice that the $e^{(1/2)x^2}$ term in this sum prohibits this solution to satisfy the definition of exponential oder. To find the limit of this solution when multiplied with e^{-x^2} as $x \to \infty$, we recognize the following:

$$
\sum_{n=0}^{\infty} \frac{x^{2n} \cdot e^{(1/2)x^2}}{(n+1)(n!)^2 2^n} = e^{x^2/2} \sum_{n=0}^{\infty} \frac{\left(\frac{x^2}{2}\right)^n}{(n+1)(n!)^2} \le e^{x^2/2} \sum_{n=0}^{\infty} \frac{\left(\frac{x^2}{4}\right)^n}{n!} = e^{x^2/2} \cdot e^{x^2/4}
$$

Which follows from the fact that:

$$
(n+1)(n!) \le 2^n \quad \forall \ n \ge 0
$$

And since the following is true:

$$
\lim_{x \to \infty} e^{-x^2} \cdot e^{x^2/2} \cdot e^{x^2/4} = 0
$$

We see that our solution is in fact, of exponential squared order. Thus, this is a solution that could not have been obtained through some other integral transforms, including the Fourier transform.

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