APPLICATIONS OF THE \mathcal{L}_2 -TRANSFORM TO PDE'S

The goal of this article is to illustrate the applicability of the \mathcal{L}_2 -transform to solving certain partial differential equations. Recall that a function $f:[0,\infty) \to \mathbb{R}$ is called *exponential squared order* if $\lim_{x\to\infty} f(x)e^{-x^2} = 0$.

Definition 1. For any exponential squared order function f(t), the \mathcal{L}_2 transform of f is defined as:

$$\mathcal{L}_{2}{f(x);s} = \int_{0}^{\infty} x e^{-x^{2}s^{2}} f(x) dx$$

Here is a useful example. For $n \ge 0$ we have:

(1)
$$\mathcal{L}_2\{x^{2n};s\} = \frac{n!}{2s^{2n+2}}$$

In the case n = 0, we obtain

$$\mathcal{L}_2\{1;s\} = \int_0^\infty x e^{-x^2 s^2} dx = \frac{1}{2s^2}$$

and for n = 1, through integration by parts, we have

$$\mathcal{L}_2\{x^{2n};s\} = \left(\frac{-x^2}{2s^2}e^{-x^2s^2}\right)\Big|_0^\infty + \frac{1}{s^2}\int_0^\infty e^{-x^2s^2}xdx = \frac{1}{s^2}\left(\frac{1}{2s^2}\right)$$

Property (1) then follows by a simple induction.

There is a differential operator δ_x , defined by

$$\delta_x = \frac{1}{x} \cdot \frac{d}{dx}$$

which has some nice properties with respect to the \mathcal{L}_2 -transform, which we now recall. See also

Proposition 1. Let f be a function of exponential squared order. Then

(2)
$$\mathcal{L}_2\{\delta_x f(x); s\} = 2s^2 \mathcal{L}_2\{f(x); s\} - f(0^+)$$

and for all $n \geq 0$

(3)
$$\mathcal{L}_2\{x^{2n}f(x);s\} = \frac{(-1)^n}{2^n} \delta_s^n \mathcal{L}_2\{f(x);s\}$$

Proof. For the first claim, we calculate

$$\int_0^\infty x e^{-x^2 s^2} \delta_x f(x) dx = \int_0^\infty x e^{-x^2 s^2} \cdot \frac{1}{x} \frac{d}{dx} f(x)(dx) = \int_0^\infty e^{-x^2 s^2} f'(x) dx$$

and, integrating by parts, we get:

$$= f(x)(e^{-x^2s^2})\Big|_0^\infty + \int_0^\infty 2xs^2xe^{-x^2s^2}f(x)dx$$

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Evaluating from 0 to ∞ , using the fact that f is exponential squared order, we can write this expression in terms of the \mathcal{L}_2 transform:

$$2s^2 \mathcal{L}_2\{f(x);s\} - f(0^+)$$

For property (3), taking the case in which n=1, we get:

$$\delta_s \mathcal{L}_2\{f(x);s\} = \delta_s \int_0^\infty x e^{-x^2 s^2} f(x) dx$$

We can take the differential operator δ_s into the integral, yielding:

$$\int_{0}^{\infty} \frac{1}{s} \frac{d}{ds} \cdot x e^{-x^{2}s^{2}} f(x) dx \Rightarrow \int_{0}^{\infty} \frac{1}{s} \cdot -2x^{2}s \cdot x e^{-x^{2}s^{2}} f(x) dx = -2 \int_{0}^{\infty} x^{2} \cdot x e^{-x^{2}s^{2}} f(x) dx$$

We can notice here that the last term of this equation is really equal to:

$$\mathcal{L}_2\{-2x^2f(x);s\}$$

Which is an alternative representation of property (3). Applying the application of the differential operator with respect to s to this result, we get:

$$\delta_s \mathcal{L}_2\{-2x^2 f(x); s\} = \delta_s - 2 \int_0^\infty x^2 x e^{-x^2 s^2} f(x) dx$$

As we did before, we re-write the differential operator and apply it within the integeral:

$$-2\int_0^\infty \frac{1}{s}\frac{d}{ds} \cdot x^2 x e^{-x^2s^2} f(x) dx = -2\int_0^\infty \frac{1}{s} x^2 x^2 x e^{-x^2s^2} f(x) - 2x^2 s dx = 4\int_0^\infty x^2 \cdot x^2 x e^{-x^2s^2} f(x) dx$$

Which we can see is realy equal to :

$$4\mathcal{L}_2\{x^4f(x);s\}$$

As we can see through induction, for a general $n \ge 1$, we have:

$$\delta_s^n \mathcal{L}_2\{f(x);s\} = -2^n \mathcal{L}_2\{x^{2n}f(x);s\}$$

Or, written alternatively,

$$\mathcal{L}_{2}\{x^{2n}f(x);s\} = \frac{(-1)^{n}}{2^{n}}\delta_{s}^{n}\mathcal{L}_{2}\{f(x);s\}$$

1. The \mathcal{L}_2 Convolution

A binary operation (\star) called the convolution of two functions f, g is defined as follows:

$$(f \star g)(t) = \int_0^t x f(\sqrt{t^2 - x^2})g(x)dx$$

It can be shown that this operation is associative and commutative. Most importantly for our purposes, the following are true:

$$\mathcal{L}_2\{f \star g; s\} = \mathcal{L}_2(f) \cdot \mathcal{L}_2(g)$$

and:

(4)
$$\mathcal{L}_2\{f_1 \star f_2 \star \dots \star f_n; s\} = \mathcal{L}_2(f_1) \cdot \mathcal{L}_2(f_2) \cdot \dots \cdot \mathcal{L}_2(f_n)$$

From which it follows:

(5)
$$\mathcal{L}^{-1}\{\hat{f}_1 \cdot \hat{f}_2 \cdot \dots \cdot \hat{f}_n\} = f_1 \star f_2 \star \dots \star f_r$$

2. Applications

Consider the following partial differential equation :

(6)
$$t^3 u_{tx} + 2xu = 0$$
 and $u(0^+, t) = 0$

where u = u(x,t) for x, t > 0 and $u(0^+, t) = \lim_{x \to 0^+} u(x,t)$. Writing the PDE in Equation 6 in terms of the differential operator, we have:

$$t^3 \frac{1}{x} \frac{d}{dx} u_t + 2u = 0$$

or equivalently,

$$t^3\delta_x u_t = -2u.$$

Taking the \mathcal{L}_2 transform of both sides and using property (3) we obtain

$$2s^2t^3\hat{u}_t - u(0^+, t) = -2\hat{u}$$

where $\hat{u} = \hat{u}(s,t) = \mathcal{L}_2\{u(x,t);s\}$. Equivalently,

$$\hat{u}_t = \frac{-1}{s^2 t^3} \hat{u} + \frac{u(0^+, t)}{2s^2 t^3}.$$

By the initial condition in (6), this last term is zero. One solution to this differential equation is

$$\hat{u}(s,t) = \frac{1}{2s^2} e^{\frac{t^{-2}s^{-2}}{2}}$$

We now write $\hat{u}(s,t)$ as a series to obtain:

$$\hat{u}(s,t) = \frac{1}{2s^2} \sum_{n=0}^{\infty} \frac{\left(\frac{s^2 t^2}{2}\right)^{-2n}}{n!} = \sum_{n=0}^{\infty} \frac{2^n}{2s^{2n+2}t^{2n}n!}.$$

Using property (1), we can calculate that $u(x,t) = \mathcal{L}_2^{-1}\{(\hat{u}(s,t);x\}$ is

$$u(x,t) = \sum_{n=0}^{\infty} \frac{2^n x^{2n}}{t^{2n} (n!)^2}$$

3. Further Generalizations

Similarly, we can solve all partial differential equations of the form:

$$0 = f(t)u + f(t)\frac{1}{x}u_x + g(t)\frac{1}{x}u_{xt}$$

Taking the \mathcal{L}_2 transform, we compute:

$$0 = f(t)\hat{u} + f(t)2s^{2}\hat{u} + g(t)2s^{2}\hat{u}_{t}$$

Rearranging:

$$\frac{\hat{u}_t}{\hat{u}} = -\frac{(1+2s^2)}{2s^2} \cdot M(t)$$

Where $M(t) = \frac{f(t)}{g(t)}$. Claiming that L(s) is any function of s, a solution for \hat{u} is as follows:

$$\hat{u}(s,t) = e^{\frac{-(1+2s^2)}{2s^2} \cdot \int_0^t M(w)dw} \cdot L(s) = e^{\int_0^t M(w)dw} \cdot e^{\frac{-\int_0^t M(w)dw}{2s^2}} \cdot L(s)$$

Writing this as a series, denoting $\int_0^t M(w) dw$ as \mathcal{M} , and letting $L(s) = \frac{1}{-s^2}$, we get:

$$\hat{u} = \frac{1}{-s^2} \sum_{n=0}^{\infty} \frac{-\mathcal{M}^n}{n! \cdot (2s^2)^n} \cdot \sum_{n=0}^{\infty} \frac{\mathcal{M}^n}{n!} = \sum_{n=0}^{\infty} \frac{\mathcal{M}^n}{n! \cdot (2^n s^{n+2})} \cdot \sum_{n=0}^{\infty} \frac{\mathcal{M}^n}{n!} = \sum_{n=0}^{\infty} \frac{\mathcal{M}^n}{n! \cdot 2^{(n-1)} \cdot (2s^{n+2})} \cdot \sum_{n=0}^{\infty} \frac{\mathcal{M}^n}{n!}$$

using identity (2), and taking the \mathcal{L}_2 inverse transform, we claim that:

$$u(x,t) = \sum_{n=0}^{\infty} \frac{\mathcal{M}^n \cdot x^{2n}}{(n!)^2 \cdot 2^{n-1}} \cdot \sum_{n=0}^{\infty} \frac{\mathcal{M}^n}{2n!}$$

Lastly, we can always solve the following types of partial differential equations:

$$0 = f(t)u + f(t)\frac{1}{x}u_x + g(t)u_t + g(t)u + xt$$

Taking the \mathcal{L}_2 transform, we get:

$$0 = \hat{u}(1+2s^{s})f(t) + \hat{u}_{t}(1+2s^{2})g(t) \Rightarrow \frac{\hat{u}_{t}}{\hat{u}} = J(t)$$

Where $J(t) = -\frac{g(t)}{f(t)}$. This implies that a solution for \hat{u} is as follows:

$$\hat{u}(s,t) = e^{\int_0^t J(w)dw} \cdot L(s)$$

Where L(s) is an arbitrary function of s. Representing this expression as a series, and letting $L(s) = \frac{1}{2s^2}$, we get:

$$\hat{u} = \sum_{n=0}^{\infty} \frac{(\int_0^t J(w)dw)^n}{n! \cdot 2y^2}$$

And after applying the \mathcal{L}_2 inverse, we get the following solution for u(x,t):

$$u(x,t) = x^0 \cdot e^{\int_0^t J(w)dw}$$

4. An Application to a Partial Differential Equation of Exponential Squared Order

Consider the following partial differential equation, with the following condition:

$$0 = g(t)u - f(t)u_t + \frac{1}{x}f(x)u_{xt} \qquad u(0^+, t) = 0$$

Writing this equation in terms of the differential operator,

$$0 = g(t)u - f(t)u_t + \delta_x f(t)u_t$$

and taking the \mathcal{L}_2 transform of it, we get:

$$0 = g(t)\hat{u}_t - f(t)\hat{u}_t + 2s^2 f(t)\hat{u}_t$$

Rearranging, we get:

$$0 = g(t)u + f(t)\hat{f}_t(-1+2s^2)$$

Which leads to:

$$\frac{\hat{u}_t}{\hat{u}} = -\frac{1}{-1+2s^2} \cdot H(t)$$

Where $H(t) = \frac{g(t)}{h(t)}$. This implies that a solution for \hat{u} is as follows:

$$\hat{u}(s,t) = e^{\frac{-1}{-1+2s^2} \cdot \int_0^t H(w) dw}$$

Writing this solution as a series, we get:

$$\hat{u}(s,t) = \sum_{n=0}^{\infty} \frac{(\int_0^t H(w)dw)^n}{n!} \cdot \left(\frac{1}{-1+2s^2}\right)^n$$

from (4), (5) and the following identity:

$$\mathcal{L}_2\{e^{ax^2};s\} = \frac{1}{-2a+2s^2}$$

We can arrive at the following solution:

$$\mathcal{L}_2^{-1}\{\hat{u}(s,t)\} = \sum_{n=1}^{\infty} \left(\frac{(\int_0^t H(w)dw)^n}{n!} \cdot (e^{(1/2)x^2})^{\star_n} \right)$$

Where $e^{(1/2)e^2}$ ^{*} represents the following:

$$\underbrace{e^{(1/2)e^2} \star e^{(1/2)e^2} \dots \star e^{(1/2)e^2}}_{n}$$

Which leads the following proposition, which can be shown through induction:

$$(e^{(1/2)e^2})^{\star_n} = \frac{1}{2^{n-1}} \cdot \frac{x^{2(n-1)} \cdot e^{(1/2)x^2}}{(n-1)!}$$

After a substitution, we have the following solution for u(x, t):

$$u(x,t) = \sum_{n=1}^{\infty} \left(\frac{(\int_{0}^{t} H(w)dw)^{n}}{n!} \cdot \frac{1}{2^{n-1}} \cdot \frac{x^{2(n-1)} \cdot e^{(1/2)x^{2}}}{(n-1)!} \right)$$

Notice that the $e^{(1/2)x^2}$ term in this sum prohibits this solution to satisfy the definition of exponential oder. To find the limit of this solution when multiplied with e^{-x^2} as $x \to \infty$, we recognize the following:

$$\sum_{n=0}^{\infty} \frac{x^{2n} \cdot e^{(1/2)x^2}}{(n+1)(n!)^2 2^n} = e^{x^2/2} \sum_{n=0}^{\infty} \frac{\left(\frac{x^2}{2}\right)^n}{(n+1)(n!)^2} \le e^{x^2/2} \sum_{n=0}^{\infty} \frac{\left(\frac{x^2}{4}\right)^n}{n!} = e^{x^2/2} \cdot e^{x^2/4}$$

Which follows from the fact that:

$$(n+1)(n!) \le 2^n \quad \forall \ n \ge 0$$

And since the following is true:

$$\lim_{x \to \infty} e^{-x^2} \cdot e^{x^2/2} \cdot e^{x^2/4} = 0$$

We see that our solution is in fact, of exponential squared order. Thus, this is a solution that could not have been obtained through some other integral transforms, including the Fourier transform.

References

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